

# **COMPUTER SIMULATION OF EQUILIBRIUM MULTICOMPONENT MULTISTAGE SEPARATION PROCESSES**

**A Thesis Submitted  
In Partial Fulfilment of the Requirements  
for the Degree of  
MASTER OF TECHNOLOGY**

**by  
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**to the  
DEPARTMENT OF CHEMICAL ENGINEERING  
INDIAN INSTITUTE OF TECHNOLOGY KANPUR  
MAY, 1985**

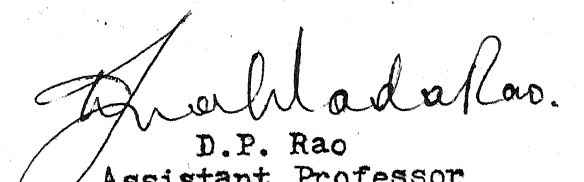
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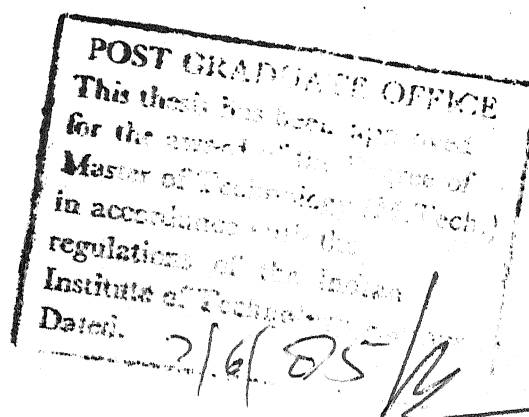
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CERTIFICATE

This is to certify that the work presented in this thesis entitled, " COMPUTER SIMULATION OF EQUILIBRIUM MULTICOMPONENT MULTISTAGE SEPARATION PROCESSES " has been carried out by Mr. Sahidul Islam under my supervision and the same has not been submitted elsewhere for a degree.

  
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I do not know how I will express my deep appreciation to our immortal beloved Newton. As a child I am trying to understand and to apply one of his principle, which is nothing compare to his major contributions, but is the heart of this thesis.

Finally what I feel that help and inspiration is as if solely from \* Marrya who boosted me and thereby helping me to think the problem, has been inducing and driving me to my ultimate long desire.

Sahidul Islam



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ABSTRACT

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The modified Thomas algorithm is employed to obtain the correction vector  $\Delta \bar{X}$  in the widely used Naphthali-Sandholm method of solving separation processes problems. An efficient algorithm for obtaining the correction  $\Delta \bar{X}$  is proposed in which the sparsity of the submatrices of the Jacobian has been exploited in the matrix multiplication and inversion. The operation count for the proposed algorithm and the standard matrix multiplication and inversion has been presented using two bench-mark problems. It has been shown that the use of the proposed algorithm results in considerable saving in the CPU time with increase in the number of components and stages. The proposed algorithm can be used for the extensions and variants of Naphthali-Sandholm methods.

## CHAPTER 1

### INTRODUCTION

The classical techniques of separation of multicomponent mixtures like distillation, absorption, extraction, etc. are widely used in chemical industries. The design or simulation of these (stage-wise) separation processes involves the solution of the material and energy balance equations and equilibrium relations for each stage, and requires an enormous amount of computational effort. Before the widespread use of computers, short-cut methods were employed for the design though these are generally inadequate for systems other than the ones for which the equilibrium relations are linear. But with accessibility to powerful computers, the rigorous methods got impetus and several methods have been proposed.

The rigorous methods of design or simulation involve two major steps; namely formulation of basic equations and their numerical methods of solution. The methods of formulation of the basic equations, in turn, can be classified as component-wise grouping of variables and stage-wise grouping of variables. The earlier methods of solution like the B-P method, the sum-rate method and the relaxation technique can be visualized as the direct substitution methods. Recently, these methods of

solution have given way to the more efficient Newton-Raphson method and its variants.

Under the component-wise grouping of variables, the basic equations can be obtained as

$$\bar{C}_i X_i = -\bar{F}_i \quad \text{for } i = 1, 2, \dots, C \quad (1)$$

for the steady state conditions; where  $\bar{C}_i$  is the coefficient matrix involving vapor and liquid flow rates and the k-values,  $\bar{X}_i$  could be either liquid or vapor mole fractions or component flow rates,  $\bar{F}_i$  are the feed component flow rates and i the components. In the relaxation technique (also known as False-Transient method) the basic equations are cast as

$$\bar{C}_i^{k+1} X^{k+1} = \bar{X}_i^k \quad i = 1, 2, \dots, C \quad (2)$$

where k is the iteration number.

More generally, the basic equations may be represented as

$$\bar{A}_i X_i = \bar{b}_i \quad i = 1, 2, \dots, C \quad (3)$$

The square matrix has the tridiagonal structure and  $\bar{X}_i$  can be found using the well known Thomas algorithm.

Equation (3) together with the enthalpy balance equations around the stages can be solved by the direct

substitution method for any assumed liquid and vapor flow rates and temperatures. The B-P method, the sum-rate method and the modified relaxation technique fall under this category.

Since the year 1965, the direct substitution methods gave way to the Newton-Raphson method (or its modified versions) of solution. In these methods, the material balance discrepancy functions,

$$M_n = \sum_{i=1}^C y_{i,n} - \sum_{i=1}^C x_{i,n} \quad n = 1, 2, \dots, N \quad (4)$$

and the enthalpy discrepancy functions around each stage are expanded in the Taylor series. Assuming the second and higher order terms to be negligible, the equations are rearranged to obtain

$$\bar{J} \Delta \bar{X} = \bar{b} \quad (5)$$

where  $\bar{J}$  is the Jacobian matrix of  $2N \times 2N$ .

Several convergence schemes and the methods of obtaining the correction vector have been proposed. These have been discussed by Holland (2).

Naphthali (4) and later Naphthali and Sandholm (5) showed that the convergence characteristics are better if the stage-wise grouping of variables together with the Newton-Raphson method are employed. For each of the stages the

variables are the component liquid flow rates, temperature and the component vapor flow rates (i.e.  $l_i, T, v_i$ ). The component and the enthalpy discrepancy functions are formulated to yield

$$\mathbf{F}(\mathbf{X}) = 0$$

Applying the Newton-Raphson technique we get

$$\mathbf{J} \Delta \mathbf{X} = -\mathbf{F}$$

The Jacobian is of the order  $(2C+1)N \times (2C+1)N$  and it has the block tridiagonal form. Several methods proposed for solving the separation problems deal with the techniques of obtaining the correction vector, Stadther [6, 7, 8].

It has been generally accepted that the Naphthali-Sandholm method has better convergence characteristics. However, it is likely to diverge if the guessed component liquid and vapor flow rates and temperatures are far from the correct values. To overcome this problem, Ketchum [3] proposed the fusion of the relaxation technique and the Naphthali-Sandholm method and demonstrated its suitability for even interlinked columns. Later Hofeling and Seader [1] have demonstrated as to how the modified Thomas algorithm can be used for the interlinked columns. Stadther [6, 7, 8] has compared the

convergence characteristics of the modified Thomas algorithm and the other methods of solution using the sparse matrix technique. He finds the Thomas algorithm as good as the other sparse matrix techniques.

From the literature, it appears that the sparsity of the submatrices (diagonal and its adjacent submatrix) has not been exploited. The objective of the present work is to propose a more efficient method of solution taking advantage of the sparsity of the submatrices.

In Chapter 2, the method of formulation of the basic equations and the method of solution is presented. The results and discussion are presented in Chapter 3. Next conclusions is presented.

## CHAPTER 2

BASIC EQUATIONS AND METHOD OF SOLUTION

In this Chapter, the strategy of formulating the basic equations involving material and enthalpy balances, equilibrium and tray efficiency relations of multistage multicomponent separation processes, and the method of obtaining solution is presented.

A model of a general stage, along with the notation employed herein, is depicted in figure 1. The various discrepancy functions can be formulated as follows:

For Material balance:

$$M_{i,n} = l_{i,n-1} + v_{i,n+1} + f_{i,n} - (1+S_n)v_{i,n} - (1+s_n)l_{i,n} \quad (1)$$

for  $1 \leq i \leq C$  &  $1 \leq n \leq N$

where  $v_{i,n}$  and  $l_{i,n}$  are the flow rates of component  $i$  in liquid and vapor leaving the  $n$ th stage, and  $S_n V_n$  and  $s_n l_n$  are the vapor and liquid side streams drawn on the  $n$ th stage.

For Enthalpy balance:

$$E_n = \sum_{i=1}^C l_{i,n-1} h_{i,n-1} + \sum_{i=1}^C v_{i,n+1} H_{i,n+1} + \sum_{i=1}^C f_{i,n} h_{F,i,n} \\ - \sum_{i=1}^C (1+S_n) v_{i,n} H_{i,n} - \sum_{i=1}^C (1+s_n) l_{i,n} h_{i,n} + q_n \dots \quad (2)$$

for  $1 \leq i \leq C$  &  $1 \leq n \leq N$



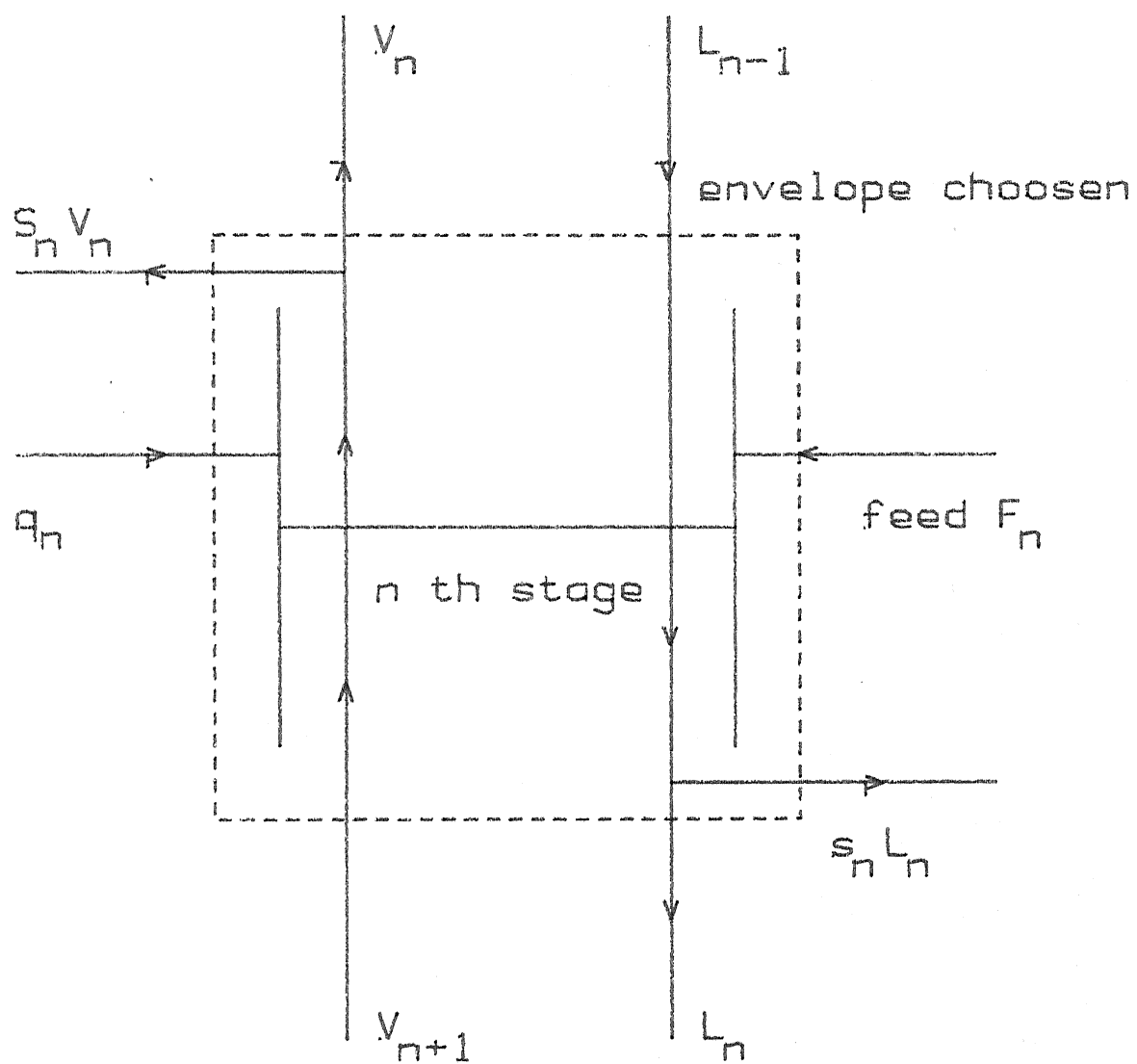


Fig. 1: A typical contacting stage

Equilibrium relations together with the Murphree efficiency:

$$O_{i,n} = \frac{\eta_n k_{i,n} l_{i,n}}{L_n} - \frac{v_{i,n}}{V_n} + (1 - \eta_n) \frac{v_{i,n+1}}{V_{n+1}} \dots \quad (3)$$

$$\text{for } 1 \leq i, j \leq C \quad \& \quad 1 \leq n \leq N$$

$$\text{where } \eta_n = \frac{y_{i,n} - y_{i,n+1}}{k_{i,n} x_{i,n} - y_{i,n+1}} \dots \quad (3a)$$

Thus, there are  $N(2C+1)$  set of nonlinear equations and they have, to be solved to obtain the  $N(2C+1)$  unknown variables, namely  $l_{i,n}$ ,  $v_{i,n}$  and  $T_n$ .

The set of equations may be compactly written as

$$\bar{F} = \bar{F}(\bar{X}) = \bar{0} \quad (4)$$

where

$$\bar{F} = [\bar{F}_1, \bar{F}_2, \dots, \bar{F}_n, \dots, \bar{F}_N]^T, \quad (5)$$

$$\bar{F}_n = [M_{1,n}, M_{2,n}, \dots, M_{C,n}, O_{1,n}, O_{2,n}, \dots, O_{C,n}, E_n]^T \quad (6)$$

$$\bar{X} = [\bar{X}_1, \bar{X}_2, \dots, \bar{X}_m]^T \quad (7)$$

$$\text{and } \bar{X}_n = [l_{1,n}, l_{2,n}, \dots, l_{C,n}, v_{1,n}, v_{2,n}, \dots, v_{C,n}, T_n]^T \quad (8)$$

It may be pointed out that the ordering of the variables is slightly different from the one proposed by Naphthali and

Sandholm 1971 . The reasons for the order chosen here is explained later.

Employing the Newton-Raphson technique, from Equation(4) we can obtain

$$\Delta \bar{X} = - \frac{\partial \bar{F}}{\partial \bar{X}}^{-1} \cdot \bar{F}$$

$$= - J^{-1} \cdot \bar{F}$$

where  $J$  is the Jacobian matrix.

The Jacobian has the block tridiagonal structure and can be represented as

$$J = \begin{bmatrix} B_1 & C_1 & & & \\ A_2 & B_2 & C_2 & & \\ & A_3 & B_3 & C_3 & \\ & & & & \\ & & & A_n & B_n & C_n \\ & & & & & B_N & C_N \end{bmatrix}$$

where

$$A_n = \frac{\partial \bar{F}_n}{\partial \bar{X}_{n-1}}, \quad B_n = \frac{\partial \bar{F}_n}{\partial \bar{X}_n} \quad \text{and} \quad C_n = \frac{\partial \bar{F}_n}{\partial \bar{X}_{n+1}}$$

and the rest of the elements are null matrices.

In expand form, the submatrix  $\bar{A}_n$  is

$$\bar{A}_n = \begin{bmatrix} \frac{\partial M_{1,n}}{\partial l_{1,n-1}} & \frac{\partial M_{1,n}}{\partial l_{2,n-1}} & \cdots & \frac{\partial M_{1,n}}{\partial l_{C,n-1}} & \cdots & \frac{\partial M_{1,n}}{\partial v_{1,n-1}} & \frac{\partial M_{1,n}}{\partial v_{C,n-1}} & \frac{\partial M_{1,n}}{\partial T_{n-1}} \\ \frac{\partial M_{2,n}}{\partial l_{1,n-1}} & \frac{\partial M_{2,n}}{\partial l_{2,n-1}} & \cdots & \frac{\partial M_{2,n}}{\partial l_{C,n-1}} & \cdots & \frac{\partial M_{2,n}}{\partial v_{1,n-1}} & \frac{\partial M_{2,n}}{\partial v_{C,n-1}} & \frac{\partial M_{2,n}}{\partial T_{n-1}} \\ \cdots & \cdots & \cdots & \cdots & \cdots & \cdots & \cdots & \cdots \\ \frac{\partial M_{C,n}}{\partial l_{1,n-1}} & \frac{\partial M_{C,n}}{\partial l_{2,n-1}} & \cdots & \frac{\partial M_{C,n}}{\partial l_{C,n-1}} & \cdots & \frac{\partial M_{C,n}}{\partial v_{1,n-1}} & \frac{\partial M_{C,n}}{\partial v_{C,n-1}} & \frac{\partial M_{C,n}}{\partial T_{n-1}} \\ \frac{\partial O_{1,n-1}}{\partial l_{1,n-1}} & \frac{\partial O_{1,n-1}}{\partial l_{2,n-1}} & \cdots & \frac{\partial O_{1,n-1}}{\partial l_{C,n-1}} & \frac{\partial O_{1,n-1}}{\partial v_{1,n-1}} & \frac{\partial O_{1,n-1}}{\partial v_{C,n-1}} & \frac{\partial O_{1,n-1}}{\partial T_{n-1}} \\ \cdots & \cdots & \cdots & \cdots & \cdots & \cdots & \cdots \\ \frac{\partial O_{C,n-1}}{\partial l_{1,n-1}} & \frac{\partial O_{C,n-1}}{\partial l_{2,n-1}} & \frac{\partial O_{C,n-1}}{\partial l_{C,n-1}} & \frac{\partial O_{C,n-1}}{\partial v_{1,n-1}} & \frac{\partial O_{C,n-1}}{\partial v_{C,n-1}} & \frac{\partial O_{C,n-1}}{\partial T_{n-1}} \\ \frac{\partial E_n}{\partial l_{1,n-1}} & \frac{\partial E_n}{\partial l_{2,n-1}} & \frac{\partial E_n}{\partial l_{C,n-1}} & \frac{\partial E_n}{\partial v_{1,n-1}} & \cdots & \frac{\partial E_n}{\partial v_{C,n-1}} & \frac{\partial E_n}{\partial T_{n-1}} \end{bmatrix}$$

$$\sigma_y = \begin{bmatrix} \bar{I}_C & \bar{O}_C & \bar{O}_C \\ \bar{O}_C & \bar{O}_C & \bar{O}_C \\ \bar{h}_C & \bar{O}_C & C_{PL} \end{bmatrix}$$

where  $\bar{I}$ ,  $\bar{O}$ ,  $\bar{O}$  are identity matrix, null matrix and null vector respectively. Subscript C indicates the dimension of the matrix or vector.  $\bar{h}$  is the liquid enthalpy vector ( $h_i, i=1, C$ ) and  $C_{PL}$  is heat capacity of  $L_{n-1}$ .

In expanded form, the submatrix  $\overset{=}{B}_n$  is

$$\overset{=}{B}_m = \begin{bmatrix} \frac{\partial M_{1,n}}{\partial l_{1,n}} & \frac{\partial M_{1,n}}{\partial l_{2,n}} & \cdots & \frac{\partial M_{1,n}}{\partial l_{C,n}} & \frac{\partial M_{1,n}}{\partial v_{1,n}} & \cdots & \frac{\partial M_{1,n}}{\partial v_{C,n}} & \frac{\partial M_{1,n}}{\partial T_n} \\ \frac{\partial M_{2,n}}{\partial l_{1,n}} & \frac{\partial M_{2,n}}{\partial l_{2,n}} & \cdots & \frac{\partial M_{2,n}}{\partial l_{C,n}} & \frac{\partial M_{2,n}}{\partial v_{1,n}} & \cdots & \frac{\partial M_{2,n}}{\partial v_{C,n}} & \frac{\partial M_{2,n}}{\partial T_n} \\ \cdots & \cdots & \cdots & \cdots & \cdots & \cdots & \cdots & \cdots \\ \frac{\partial M_{C,n}}{\partial l_{1,n}} & \frac{\partial M_{C,n}}{\partial l_{2,n}} & \cdots & \frac{\partial M_{C,n}}{\partial l_{C,n}} & \frac{\partial M_{C,n}}{\partial v_{1,n}} & \cdots & \frac{\partial M_{C,n}}{\partial v_{C,n}} & \frac{\partial M_{C,n}}{\partial T_m} \\ \frac{\partial O_{1,n}}{\partial l_{1,n}} & \frac{\partial O_{1,n}}{\partial l_{2,n}} & \cdots & \frac{\partial O_{1,n}}{\partial l_{C,n}} & \frac{\partial O_{1,n}}{\partial v_{1,n}} & \cdots & \frac{\partial O_{1,n}}{\partial v_{C,n}} & \frac{\partial O_{1,n}}{\partial T_n} \\ \cdots & \cdots & \cdots & \cdots & \cdots & \cdots & \cdots & \cdots \\ \frac{\partial O_{C,n}}{\partial l_{1,n}} & \frac{\partial O_{C,n}}{\partial l_{2,n}} & \cdots & \frac{\partial O_{C,n}}{\partial l_{C,n}} & \frac{\partial O_{C,n}}{\partial v_{1,n}} & \cdots & \frac{\partial O_{C,n}}{\partial v_{C,n}} & \frac{\partial O_{C,n}}{\partial T_n} \\ \frac{\partial E_n}{\partial l_{1,n}} & \frac{\partial E_n}{\partial l_{2,n}} & \cdots & \frac{\partial E_n}{\partial l_{C,n}} & \frac{\partial E_n}{\partial v_{1,n}} & \cdots & \frac{\partial E_n}{\partial v_{C,n}} & \frac{\partial E_m}{\partial T_n} \end{bmatrix}$$

and can be simplified to yield

$$\bar{B}_n = \begin{bmatrix} \begin{array}{l} -(1+s_n) \text{ only diagonal} \\ \text{element of block} \\ \text{submatrix } -(1+s_n) \end{array} & \begin{array}{l} -(1+S_n) \text{ only diagonal} \\ \text{elements of} \\ \text{block submatrix} \\ \text{same element} \\ -(1+S_n) \end{array} \\ \hline \begin{array}{l} \text{Totally filled} \\ \text{submatrix} \end{array} & \begin{array}{l} \text{Totally filled} \\ \text{submatrix} \end{array} \\ h_1 \dots h_c & H_1 \dots H_C \end{bmatrix} *$$

$$\alpha, \bar{B}_n = \begin{bmatrix} -(1+s_n) \bar{I}_C & (1+S_n) \bar{I}_C & \bar{O}_C \\ \bar{X}_C & \bar{X}_C & \bar{X}_C \\ (1+s_n) \bar{h}_C & (1+s_n) \bar{H}_C & \bar{C}_{PLV} \end{bmatrix}$$

where  $\bar{X}$ ,  $\bar{X}$  and  $X$  denote the filled matrix, vector and nonzero element respectively and the subscript C the orders of the matrix or vector.

$$\begin{aligned}
C_n = & \left[ \begin{array}{cccccc}
\frac{\partial^{M_{1,n}}}{\partial^{I_{1,n+1}}}, \frac{\partial^{M_{1,n}}}{\partial^{I_{2,n+1}}} & \cdots & \frac{\partial^{M_{1,n}}}{\partial^{I_{C,n+1}}}, \frac{\partial^{M_{1,n}}}{\partial^{V_{1,n+1}}} & \cdots & \frac{\partial^{M_{1,n}}}{\partial^{V_{C,n+1}}}, \frac{\partial^{M_{1,n}}}{\partial^{T_{n+1}}} \\
\frac{\partial^{M_{2,n}}}{\partial^{I_{1,n+1}}}, \frac{\partial^{M_{2,n}}}{\partial^{I_{2,n+1}}} & \cdots & \frac{\partial^{M_{2,n}}}{\partial^{I_{C,n+1}}}, \frac{\partial^{M_{2,n}}}{\partial^{V_{1,n+1}}} & \cdots & \frac{\partial^{M_{2,n}}}{\partial^{V_{C,n+1}}}, \frac{\partial^{M_{2,n}}}{\partial^{T_{n+1}}} \\
\cdots & \cdots & \cdots & \cdots & \cdots & \cdots \\
\frac{\partial^{M_{C,n}}}{\partial^{I_{1,n+1}}}, \frac{\partial^{M_{C,n}}}{\partial^{I_{2,n+1}}} & \cdots & \frac{\partial^{M_{C,n}}}{\partial^{I_{C,n+1}}}, \frac{\partial^{M_{C,n}}}{\partial^{V_{1,n+1}}} & \cdots & \frac{\partial^{M_{C,n}}}{\partial^{V_{C,n+1}}}, \frac{\partial^{M_{C,n}}}{\partial^{T_{n+1}}} \\
\frac{\partial^{O_{1,n}}}{\partial^{I_{1,n+1}}}, \frac{\partial^{O_{1,n}}}{\partial^{I_{1,n+1}}} & \cdots & \frac{\partial^{O_{1,n}}}{\partial^{I_{1,n+1}}}, \frac{\partial^{O_{1,n}}}{\partial^{V_{1,n+1}}} & \cdots & \frac{\partial^{O_{1,n}}}{\partial^{V_{1,n+1}}}, \frac{\partial^{O_{1,n}}}{\partial^{T_{n+1}}} \\
\cdots & \cdots & \cdots & \cdots & \cdots & \cdots \\
\frac{\partial^{O_{C,n}}}{\partial^{I_{1,n+1}}}, \frac{\partial^{O_{C,n}}}{\partial^{I_{2,n+1}}} & \cdots & \frac{\partial^{O_{C,n}}}{\partial^{I_{C,n+1}}}, \frac{\partial^{O_{C,n}}}{\partial^{V_{1,n+1}}} & \cdots & \frac{\partial^{O_{C,n}}}{\partial^{V_{C,n+1}}}, \frac{\partial^{O_{C,n}}}{\partial^{T_{n+1}}} \\
\frac{\partial^{E_n}}{\partial^{I_{1,n+1}}}, \frac{\partial^{E_n}}{\partial^{I_{2,n+1}}} & \cdots & \frac{\partial^{E_n}}{\partial^{I_{C,n+1}}}, \frac{\partial^{E_n}}{\partial^{V_{1,n+1}}} & \cdots & \frac{\partial^{E_n}}{\partial^{V_{C,n+1}}}, \frac{\partial^{E_n}}{\partial^{T_{n+1}}}
\end{array} \right]
\end{aligned}$$

$$\begin{array}{c}
 \bar{C}_n = \left[ \begin{array}{cc}
 \text{unit block submatrix} & \text{null column vector} \\
 \hline
 \text{null block matrix} & \text{Totally filled block sub matrix} \\
 & H_{1,n+1} \dots H_{C,n+1}
 \end{array} \right] *
 \end{array}$$

and can be simplified to get

$$\begin{bmatrix}
 \bar{O}_C & \bar{I}_C & \bar{O}_C \\
 \bar{O}_C & \bar{X}_C & \bar{O}_C \\
 \bar{O}_C & \bar{H}_C & C_{AV}
 \end{bmatrix}$$



THOMAS ALGORITHM

The correction vector  $\Delta \bar{X}$  can be found by the Thomas algorithm and is given below

Forward Substitution:

For the stage 1

$$\begin{aligned} \text{Steps: } 1 \quad \bar{P}_1 &\leftarrow (\bar{B}_1)^{-1} \bar{C}_1 \\ : 2 \quad \bar{Q}_1 &\leftarrow (\bar{B}_1)^{-1} \bar{F}_1 \end{aligned}$$

For the stages n from 2 to (N-1)

$$\begin{aligned} : 3 \quad \bar{P}_n &\leftarrow (\bar{B}_n - \bar{A}_n \bar{P}_{n-1})^{-1} \bar{C}_n \\ : 4 \quad \bar{Q}_n &\leftarrow (\bar{B}_n - \bar{A}_n \bar{P}_{n-1})^{-1} (\bar{F}_n - \bar{A}_n \bar{Q}_{n-1}) \end{aligned}$$

For the last stage N

$$: 5 \quad \bar{Q}_N \leftarrow (\bar{B}_N - \bar{A}_N \bar{P}_{N-1})^{-1} (\bar{F}_N - \bar{A}_N \bar{Q}_{N-1})$$

Backward substitution

$$: 6 \quad \Delta \bar{X}_N \leftarrow \bar{Q}_N$$

For the stages n from N-1 to 1

$$: 7 \quad \Delta \bar{X}_n \leftarrow -(\bar{Q}_n - \bar{P}_n \bar{X}_{n+1})$$

It can be seen that the algorithm involves several time taking matrix multiplications and inversions. Advantage of the sparcity and the structure of these matrices can be taken to minimise the machine operations, as described below.

In step 1 and 3, we encounter the matrix multiplications  $(\bar{B})^{-1} \bar{C}_1$  and  $(\bar{B}_j - \bar{A}_j \bar{P}_j)^{-1} \bar{C}_j$ . The inverted matrices are totally filled while  $\bar{C}_1$  and  $\bar{C}_j$  are highly sparse. The structure of the resulting matrix is

$$\begin{bmatrix} \text{Filled} \\ \text{matrix} \end{bmatrix} \begin{bmatrix} \bar{O}_C & \bar{I}_C & \bar{O}_C \\ \bar{O}_C & \bar{X}_C & \bar{O}_C \\ \bar{O}_C & \bar{X}_C & X \end{bmatrix} = \begin{bmatrix} \bar{O}_C & \bar{X}_C & \bar{X}_C \\ \bar{O}_C & \bar{X}_C & \bar{X}_C \\ \bar{O}_C & \bar{X}_C & X \end{bmatrix}$$

$$(\bar{B})^{-1} \text{ or } (\bar{B} - \bar{A}_j \bar{P}_{j-1})^{-1} \bar{C}_j \quad \bar{P}_j$$

where  $\bar{X}$ ,  $\bar{X}$  and  $X$  denote the filled matrix, vector and non-zero element respectively,  $\bar{O}$  and  $\bar{I}$  are the null and identity matrices, and the subscript  $C$  the order of the matrix or vector.

It can be seen that there is no need to compute the elements of the first  $C$  columns of the resulting matrix and we can save  $C(2C+1)^2$  operations. Further, the next  $C$  columns can be found as

$$P_{j,C+i} = b_{j,i+C}^I + \sum_{k=C+1}^{2C+1} b_{j,k}^I C_{k,C+i} \quad \text{for } 1 \leq j \leq 2C+1, 1 \leq i \leq C \quad (3)$$

The elements of the last column are

$$P_{j,2C+1} = b_{j,2C+1}^I C_{2C+1,2C+1} \quad (4)$$

Thus the operation count of this matrix multiplication is  $(C^2+1)(2C+1)$  instead of  $(2C+1)^3$  required for standard matrix multiplication.

The matrix multiplication  $\overline{A}_j \overline{P}_{j-1} (= \overline{\alpha}_j)$  carried out taking the advantage of sparsity as given below.

$$\begin{bmatrix} \overline{I}_C & \overline{O}_C & \overline{O}_C \\ \overline{O}_C & \overline{O}_C & \overline{O}_C \\ \overline{h}_C & \overline{O} & C_{PL} \\ & \overline{A}_n & \end{bmatrix} \begin{bmatrix} \overline{O}_C & \overline{X}_C & \overline{X}_C \\ \overline{O}_C & \overline{X}_C & \overline{X}_C \\ \overline{O}_C & \overline{X}_C & X \\ & \overline{P}_{n-1} & \end{bmatrix} = \begin{bmatrix} \overline{O}_C & \overline{X}_C & \overline{X}_C \\ \overline{O}_C & \overline{O}_C & \overline{O}_C \\ \overline{O}_C & \overline{X}_C & X \\ & \overline{\alpha}_n & \end{bmatrix} \quad (5)$$

Here, only the  $\overline{X}_C$ ,  $X$  in the row need to be computed.

The nonzero elements of  $\overline{\alpha}_n$  are:

$$\alpha_{j,C+i} = P_{j,C+i} \quad \text{for } 1 \leq j \leq C+1 \quad (6) \\ 1 \leq i \leq C$$

$$\alpha_{2C+1,C+i} = \sum_{k=1}^C A_{2C+1,k} P_{k,C+i} + A_{2C+1,2C+1} P_{2C+1,C+i} \\ \text{for } 1 \leq i \leq C+1 \quad (7)$$

Thus we need to perform only  $(C+1)^2$  scalar multiplication in stead of  $(2C+1)^3$ .

The product  $\bar{A}_n \bar{F}_{n-1} = \bar{\beta}_{n-1}$  may be found as follows

$$\begin{array}{ccc} \begin{array}{c} \bar{I}_C \\ \bar{O}_C \\ \bar{H}_C \end{array} & \begin{array}{c} \bar{O}_C \\ \bar{O}_C \\ \bar{O}_C \end{array} & \begin{array}{c} \bar{O}_C \\ \bar{O}_C \\ c_{PL} \end{array} \\ \bar{A} & & \end{array} \begin{array}{c} \bar{F}_C \\ \bar{F}_C \\ F \end{array} = \begin{array}{c} \bar{F}_C \\ \bar{O}_C \\ f \end{array} \quad \bar{F}$$

where  $\beta_j = \bar{F}_j$  for  $1 \leq j \leq C$  (8)

$$\beta_{2C+1} = \sum_{k=1}^C A_{2C+1,k} F_k + A_{2C+1,2C+1} F_{2C+1} \quad (9)$$

only the last element need to be computed; thus only  $C+1$  operations are required instead of  $(2C+1)^2$  operations for the standard matrix multiplication. In backward substitution, the multiplication  $P_n X_{n+1}$  involves  $(2C+1)(C+1)$  since the first  $C$  columns are zero elements.

Inversion of  $(\bar{B}_n - \bar{A}_n \bar{P}_{n-1})$  by partitioning.

Inversion by partitioning does not save the operations to be performed. But from the structure of the matrix  $(\bar{B}_n - \bar{A}_n \bar{P}_{n-1})$  some saving in operations can be realised as shown below.

$$(\bar{B}_n - \bar{A}_n \bar{P}_{n-1}) = \bar{b} = \begin{bmatrix} (1+s_n)I_C & \bar{X}_C & \bar{X}_C \\ \bar{X}_C & \bar{X}_C & \bar{X}_C \\ \bar{X}_C & \bar{X}_C & X \end{bmatrix}$$

$$= \begin{bmatrix} \bar{b}_{11} & \bar{b}_{12} \\ \bar{b}_{21} & b_{22} \end{bmatrix}$$

The inverse is given by

$$\bar{b}^{-1} = \begin{bmatrix} \bar{D}_{11} & \bar{D}_{12} \\ \bar{D}_{21} & D_{22} \end{bmatrix}$$

$$\text{where } \bar{D}_{11} = (\bar{b}_{11})^{-1} + (\bar{b}_{11})^{-1} \bar{b}_{12} D_{22} \bar{b}_{21} (\bar{b}_{11})^{-1}$$

$$\bar{D}_{12} = -(\bar{b}_{11})^{-1} \bar{b}_{12} D_{22}$$

$$\bar{D}_{21} = -D_{22} \bar{b}_{21} (\bar{b}_{11})^{-1}$$

$$D_{22} = (b_{22} - \bar{b}_{21} (\bar{b}_{11})^{-1} \bar{b}_{12})^{-1}$$

The inverse of  $\bar{b}_{11}$  can, in turn, be found by partitioning as given below.

$$\bar{b}_{11} = \begin{bmatrix} (1+s_n) \bar{I}_C & \bar{X}_C \\ \bar{X}_C & \bar{X}_C \end{bmatrix} = \begin{bmatrix} \bar{d}_{11} & \bar{d}_{12} \\ \bar{d}_{21} & \bar{d}_{22} \end{bmatrix}$$

$$(\bar{b}_{11})^{-1} = \begin{bmatrix} \bar{e}_{11} & \bar{e}_{12} \\ \bar{e}_{21} & \bar{e}_{22} \end{bmatrix}$$

where

$$\begin{aligned}\bar{e}_{11} &= (\bar{a}_{11})^{-1} + (\bar{a}_{11})^{-1} \bar{a}_{12} \bar{e}_{22} \bar{a}_{21} (\bar{a}_{11})^{-1} \\ \bar{e}_{12} &= -(\bar{a}_{11})^{-1} \bar{a}_{12} \bar{e}_{22} \\ \bar{e}_{21} &= -\bar{e}_{22} \bar{a}_{21} (\bar{a}_{11})^{-1} \\ \bar{e}_{22} &= (\bar{a}_{22} - \bar{a}_{21} (\bar{a}_{11})^{-1} \bar{a}_{12})^{-1}\end{aligned}$$

It may be noted  $\bar{a}_{11}$  is a diagonal matrix and its inversion can be obtained by simply taking the reciprocal of each of the diagonal elements. Thus to find the inverse of a matrix of  $2C+1$ , we need only the standard inversion of matrix of order  $C$  and some matrix multiplications.

	Operation Count	Standard operation	Saving
$\overline{P}_j$	$(C^2+1)(2C+1)$ $= 2C^3 + C^2 + 2C+1$	$(2C+1)^3$ $= 8C^3 + 12C^2 + 6C+1$	$6C^3 + 11C^2 + 4C$
$j$	$(C+1)^2$ $= C^2+2C+1$	$8C^3 + 12C^2 + 6C+1$	$8C^3 + 11C^2 + 4C+1$
$j$	$(C+1)$	$(2C+1)^2$ $= 4C^2 + 4C+1$	$4C^2 + 3C$
$P_n$	$X_n$ $2C^2 + 3C+1$	$4C^2 + 4C+1$	$2C^2 + C$
Inv	$5C^3 + 14C^2 + 6C$	$8C^3 + 12C^2 + 6C+1$	$3C^3 - 2C^2 + 1$
$P_j$	$(N-1)(2C^3 + C^2 + 2C+1)$	$(N-1)(8C^3 + 12C^2 + 6C+1)$	
$j$	$N (C^2 + 2C + 1)$	$N (8C^3 + 12C^2 + 6C+1)$	
$j$	$N (C + 1)$	$N (4C^2 + 4C+1)$	
$n$	$X_n (N-1)(C^2 + 2C+1)$	$(N-1)(4C^2 + 4C+1)$	
Inv	$N(5C^3 + 14C^2 + 6C)$	$N (8C^3 + 12C^2 + 6C+1)$	
Total count	$3N(5C^3 + 15C^2 + 9C+2)$ $+ 2(N-1)(2C^3 + 2C^2 + 3C+1)$	$3N(16C^3 + 28C^2 + 16C+3)$ $+ 2(N-1)(8C^3 + 16C^2 + 10C+2)$	$3N(11C^3 + 13C^2)$ $+ 7C+1)$ $+ 2(N-1)(6C^3 + 14C^2 + 7C+1)$

## CHAPTER 3

RESULTS AND DISCUSSION

The algorithm proposed in the previous chapter has been implemented in FORTRAN 10 on the DEC 10 system. First, the saving in CPU time for inventing the matrix  $(\bar{B}_n - \bar{A}_n \bar{C}_{n-1})$  has been examined. The efficiency of the proposed method has been tested by solving two absorption problems and the details are presented in this chapter.

It is known that the inversion of matrix by partition does not result in saving the CPU time. But, the structure matrix in these separation process problems is such that we need to invert only  $C \times C$  matrix to get the inversion of  $(2C+1) \times (2C+1)$ . This is so because the other submatrix, obtained on partitioning, whose inverse to be found to found is either identity matrix or a diagonal matrix with only a few elements which are other than one. Thus some CPU time saving can be achieved. As shown in the previous Chapter, the operation count for the inversion for a problem involving  $C$  components is  $(5C^3 + 14C^2 + 5C)$  compared the standard inversion (i.e. either by the Gaussian elimination or the Gauss-Jordon elimination) which is  $(2C+1)^3$ .



TABLE 2

SAMPLE PROBLEM NO.1 Taken from [3]

Absorption column having 20 plates and 4 component system:

Component	Rich gas $v_{N+1,i}$ mole/hr	Absorbing liq. $l_{o,i}$ mole/hr	
A	75.0	0.0	
B	15.0	0.0	Absorbing liq. temp. = 125°C
C	10.0	0.0	Entering rich gas temp. = 200°C
D	0.0	100.0	

Find the temperature and flow rates of the components of vapor and liquid stream leaving from the column.

TABLE 3

## SAMPLE PROBLEM No.2

## STATEMENT OF THE PROBLEM

COMPONENT	RICH GAS $v_{N+1,i}$ (mol/h)	Lean Oil $l_{o,i}$ (mol/h)	OTHER SPECIFICATIONS
CO <sub>2</sub>	0.4703	0.0	$T_o = 2.9^\circ\text{F}$ , $T_{N+1} = 0^\circ\text{F}$ ,
N <sub>2</sub>	0.1822	0.0	$N = 8$ , and
CH <sub>4</sub>	88.7000	0.0	$P = 800 \text{ lb/in}^2 \text{ abs}$
C <sub>2</sub> H <sub>6</sub>	6.6747	0.0	initial temperature
C <sub>3</sub> H <sub>8</sub>	2.7786	0.0015	profile to be constant
i C <sub>4</sub> H <sub>10</sub>	0.6375	0.0006	at $T_j = 25^\circ\text{F}$
n C <sub>4</sub> H <sub>10</sub>	0.3655	0.0013	for all $j$ ( $j = 1, 2, \dots, N$ ).
i C <sub>5</sub> H <sub>12</sub>	0.1158	0.0067	The initial vapor rate
n C <sub>5</sub> H <sub>12</sub>	0.0505	0.0061	profile is to be constant
C <sub>6</sub> H <sub>14</sub>	0.0146	0.1495	at $V_j = 90.88$ ( $j = 1, 2, \dots, 8$ )
C <sub>7</sub> H <sub>16</sub>	0.0081	0.5736	and the liquid rates are
C <sub>8</sub> H <sub>18</sub>	0.002	1.8214	$L_j = 6.3095$ ( $j = 1, 2, \dots, 8$ )
C <sub>9</sub> H <sub>20</sub>	0.000	1.6866	and $L_8 = 15.42$
C <sub>10</sub> H <sub>22</sub>	0.000	2.0619	

TABLE-5

INITIAL CHECKS OF FLOW RATES AND TEMPERATURE ARE:

WIND PHASE CORRECTION FLOW RATES ARE

CORRECTION NO. STAGE NOS. ARE

1	2	3	4	5	6	7	8
42380E+00	42410E+00	42400E+00	42400E+00	42410E+00	42420E+00	42430E+00	42480E+00
16510E+00	16430E+00	16430E+00	16430E+00	16430E+00	16430E+00	16440E+00	16440E+00
80280E+00	80000E+00	79970E+00	79970E+00	79980E+00	80000E+00	80030E+00	80120E+00
59080E+00	60100E+00	60100E+00	60100E+00	60190E+00	60200E+00	60220E+00	60290E+00
23880E+00	23900E+00	23900E+00	23900E+00	25060E+00	25060E+00	25070E+00	25100E+00
57760E+00	57760E+00	57760E+00	57760E+00	57950E+00	57960E+00	57960E+00	57980E+00
27850E+00	22650E+00	32810E+00	32920E+00	32950E+00	32960E+00	32960E+00	33010E+00
74790E+00	18270E+00	10110E+00	10330E+00	10400E+00	10430E+00	10440E+00	10440E+00
16160E+00	10370E+00	10110E+00	43680E+00	44840E+00	45240E+00	45440E+00	45570E+00
17480E+00	17300E+00	17280E+00	17280E+00	17100E+00	16690E+00	15460E+00	13780E+00
24170E+00	24000E+00	23600E+00	23600E+00	23900E+00	23920E+00	23920E+00	20550E+00
18230E+00	18100E+00	18090E+00	18090E+00	18090E+00	18070E+00	17850E+00	15970E+00
82260E+00	63110E+00	61790E+00	61790E+00	61800E+00	61800E+00	61760E+00	59840E+00

WIND CORRECTION FLOW RATES ARE

CORRECTION NO. STAGE NOS. ARE

1	2	3	4	5	6	7	8
3360E+00	34030E+00	33700E+00	34170E+00	34330E+00	34660E+00	35750E+00	17640E+00
37820E+00	37460E+00	37500E+00	37640E+00	37890E+00	38400E+00	10010E+00	26840E+00
10570E+00	10580E+00	10570E+00	10610E+00	10690E+00	10680E+00	31370E+00	84150E+00
13870E+00	13870E+00	13870E+00	13490E+00	13520E+00	13590E+00	10860E+00	29140E+00
58070E+00	62200E+00	64620E+00	65370E+00	65940E+00	66340E+00	13820E+00	18090E+00
25230E+00	31500E+00	33750E+00	34590E+00	34880E+00	35150E+00	55130E+00	14790E+00
13770E+00	17600E+00	11570E+00	20230E+00	21630E+00	20980E+00	21420E+00	57580E+00
12400E+00	11090E+00	11080E+00	10330E+00	91830E+00	78120E+00	46810E+00	11050E+00
15000E+00	15000E+00	15000E+00	16250E+00	16260E+00	16320E+00	16300E+00	95580E+00
15000E+00	15000E+00	15000E+00	16250E+00	16260E+00	16320E+00	16300E+00	36430E+00
15000E+00	15000E+00	15000E+00	16250E+00	16260E+00	16320E+00	16300E+00	48880E+00

Table 5 (continued)

[illegible]

Table 5 (continued)

```

      APP AFTER MASS BALANCE= 0.86256+02
      J= 6      AEF0F POTHAIDV = 0.1872E+11
      ITERATION NUMBER= 1

      APP AFTER MASS BALANCE= 0.2046E-11
      J= 6      AEF0F POTHAIDV = 0.6312E+06
      ITERATION NUMBER= 2

      APP AFTER MASS BALANCE= 0.2471E-11
      J= 6      AEF0F POTHAIDV = 0.7279E+05
      ITERATION NUMBER= 2

      APP AFTER MASS BALANCE= 0.2617E-11
      J= 6      AEF0F POTHAIDV = 0.5145E+03
      ITERATION NUMBER= 4

      APP AFTER MASS BALANCE= 0.1785E-11
      J= 6      AEF0F POTHAIDV = 0.8651E-03
      ITERATION NUMBER= 5

      APP AFTER MASS BALANCE= 0.4281E-11
      J= 6      AEF0F POTHAIDV = 0.5948E-03
      SUCCESSFUL CONVERGENCE
      ITERATION NUMBER= 5

```



Table 5 (continued)

VAPOR AND LIQUID RATE AND TEMPERATURE ARE

STAGE NUMBER	VAPOR RATE	LIQUID RATE	TEMPERATURE
1	0.89823526E+02	0.10938037E+02	0.50106360E+03
2	0.84153396E+02	0.11248682E+02	0.50395584E+03
3	0.844763697E+02	0.11502861E+02	0.50320764E+03
4	0.85017798E+02	0.11788229E+02	0.50124028E+03
5	0.85493165E+02	0.12215641E+02	0.49855777E+03
6	0.95871336E+02	0.12701652E+02	0.49504246E+03
7	0.98216577E+02	0.13696913E+02	0.49003263E+03
8	0.87211838E+02	0.16484876E+02	0.48148252E+03

OUTPUT OF PROB. NO. 1

TABLE 6

[illegible]



Table 6 (continued)

[illegible]

STAGE NO.	TOTAL	LIO.	RATE	TOTAL	VAP.	RATE	TEMPERATURE
1	0.05316391	0.0333	0.0333	0.05223615	0.0222	1446	
2	0.10686150	0.0333	0.0333	0.05223615	0.0222	1478	
3	0.10735486	0.0333	0.0333	0.05223615	0.0222	1525	
4	0.10861350	0.0333	0.0333	0.05223615	0.0222	1552	
5	0.10933991	0.0333	0.0333	0.05223615	0.0222	1602	
6	0.11094421	0.0333	0.0333	0.05223615	0.0222	1662	
7	0.11109421	0.0333	0.0333	0.05223615	0.0222	1736	
8	0.11112739	0.0333	0.0333	0.05223615	0.0222	1790	
9	0.11113501	0.0333	0.0333	0.05223615	0.0222	1820	
10	0.11115200	0.0333	0.0333	0.05223615	0.0222	1850	
11	0.11115750	0.0333	0.0333	0.05223615	0.0222	1881	
12	0.11116498	0.0333	0.0333	0.05223615	0.0222	1941	
13	0.11117244	0.0333	0.0333	0.05223615	0.0222	1971	
14	0.11117988	0.0333	0.0333	0.05223615	0.0222	2044	
15	0.11118727	0.0333	0.0333	0.05223615	0.0222	2119	
16	0.11119476	0.0333	0.0333	0.05223615	0.0222	2190	
17	0.11120220	0.0333	0.0333	0.05223615	0.0222	2262	
18	0.11120963	0.0333	0.0333	0.05223615	0.0222	2335	
19	0.11121706	0.0333	0.0333	0.05223615	0.0222	2408	
20	0.11122449	0.0333	0.0333	0.05223615	0.0222	2481	
21	0.11123192	0.0333	0.0333	0.05223615	0.0222	2554	
22	0.11123935	0.0333	0.0333	0.05223615	0.0222	2627	
23	0.11124678	0.0333	0.0333	0.05223615	0.0222	2700	
24	0.11125421	0.0333	0.0333	0.05223615	0.0222	2773	
25	0.11126164	0.0333	0.0333	0.05223615	0.0222	2846	
26	0.11126907	0.0333	0.0333	0.05223615	0.0222	2919	
27	0.11127650	0.0333	0.0333	0.05223615	0.0222	2992	
28	0.11128393	0.0333	0.0333	0.05223615	0.0222	3065	
29	0.11129136	0.0333	0.0333	0.05223615	0.0222	3138	
30	0.11129879	0.0333	0.0333	0.05223615	0.0222	3211	
31	0.11130622	0.0333	0.0333	0.05223615	0.0222	3284	
32	0.11131365	0.0333	0.0333	0.05223615	0.0222	3357	
33	0.11132108	0.0333	0.0333	0.05223615	0.0222	3430	
34	0.11132851	0.0333	0.0333	0.05223615	0.0222	3503	
35	0.11133594	0.0333	0.0333	0.05223615	0.0222	3576	
36	0.11134337	0.0333	0.0333	0.05223615	0.0222	3649	
37	0.11135080	0.0333	0.0333	0.05223615	0.0222	3722	
38	0.11135823	0.0333	0.0333	0.05223615	0.0222	3795	
39	0.11136566	0.0333	0.0333	0.05223615	0.0222	3868	
40	0.11137309	0.0333	0.0333	0.05223615	0.0222	3941	
41	0.11138052	0.0333	0.0333	0.05223615	0.0222	4014	
42	0.11138795	0.0333	0.0333	0.05223615	0.0222	4087	
43	0.11139538	0.0333	0.0333	0.05223615	0.0222	4160	
44	0.11140281						

```

ITERATION NUMBER= 1 BALANCE= 0.9920E-11
AEF AFTER MASS BALANCE= 0.9920E-11
AEF AFTER MASS BALANCE= 0.9920E-11
AEF AFTER MASS BALANCE= 0.1083E-10
J= 20 AEF OF ENTHALPY = 0.3438E-03

ITERATION NUMBER= 2 BALANCE= 0.2093E-10
AEF AFTER MASS BALANCE= 0.2095E-10
AEF AFTER MASS BALANCE= 0.2096E-10
AEF AFTER MASS BALANCE= 0.2096E-10
J= 20 AEF OF ENTHALPY = 0.2143E-09

SUCCESSFUL CONVERGENT
ITERATION NUMBER= 2

```

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To get actual CPU time savings, numerical experiments were carried out using the test matrix of the type that are encountered in the separation process problems. The test matrices are tabulated in Appendix (D) . The CPU time required for the inversion by partition and by the Gauss-Jordon elimination have been compared for different values of C and presented in Table 1.

The saving in CPU time is becoming increasingly significant as the C increases if the proposed method is employed.

An absorption problem given by Naphthali-Sandholm 3 and another absorption problem given by Holland 1 have been chosen for testing the efficiency of the proposed method. In the first problem, the total number components of the mixture are four and the number stages are twenty. In the other problem the number components are fourteen and stages are eight. The details of the problems are given in Table 2 and 3 and the equilibrium and enthalpy data are given in Appendices B & C. The elements of the Jacobian matrix (the partial derivatives) have been evaluated analytically. The analytical expressions for the derivatives are given in Appendix (A & E).

The two problems have been solved exploiting the sparsity of the submatrices and employing the 'standard' matrix operations. Since no approximations were made while taking of the sparsity in computation, the number of iteration required identical in both the methods. The CPU time required to solve the two problems by these two methods alongwith other details are given in Table 4.

Table 4 shows a substantial reduction in CPU time is achieved in the proposed method. The saving in CPU time becomes increasingly significant as the number of components increases. The proposed method can be employed even interlinked columns.

## CHAPTER 4

CONCLUSIONS

An efficient algorithm for solving the separation processes problems by the well known Naphthali-Sandholm method has been presented. In this algorithm the sparsity the sub-matrices of the Jacobian matrix is exploited in the matrix multiplications and in the inversion of the matrices  $(\bar{B}_n - \bar{A}_n \bar{C}_{n-1})$ . It has been shown that the operation count for the proposed algorithm is  $(50^3 + 140^2 + 60)$  compared to  $(20+1)^3$  with the standard matrix operations. By solving two 'bench-mark' problems, it has been shown that the saving in the CPU time becomes increasingly significant as the number components involved becomes large. In the proposed algorithm, the saving in CPU time in computing the correction vector  $\bar{A} \bar{X}$  is effected, but the number<sup>of</sup> iteration required is the same as with the use of standard matrix operations.

The algorithm can be extended for solving interlinked column employing the method suggested by Hocling and Seader. The computer code need to be tested to determine its effectiveness for distillation of nonideal mixtures, extraction and adsorption problems.

NOMENCLATURE

$A_j$	Submatrices of Jacobian Matrix at the jth row
$B_j$	Submatrices of Jacobian Matrix at the jth row
$C_j$	Submatrices of Jacobian Matrix at the jth row
$C$	Total number of components involved
$L_j$	Overall molar liquid flow rate from jth stage
$V_j$	Overall molar Vapor flow rate from jth stage
$l_{ij}$	Molar liquid flow rate of component i from jth stage
$v_{ij}$	Molar vapor flow rate of component i from jth stage
$K_{ij}$	Distribution coefficient of ith component at jth stage
$\bar{X}$	Vector of variables
$J$	Jacobian matrix
$f_{ij}$	Molar feed rate of the component i into the jth stage
$\bar{F}$	Residual vector
$\bar{F}_j$	Residual vector for the jth stage
$P_j$	P matrix in the Thomas algorithm
$q_j$	External heat input into the jth stage
$h_{li}$	Molar specific liquid phase enthalpy of component i
$H_i$	Molar specific vapor phase enthalpy of component i
$h_{f,i,j}$	Molar specific feed enthalpies of component i
$N$	Total number of stages
$M_{ij}$	Mass balance discrepancy of component i for jth stage

$O_{ij}$	Equilibrium relation discrepancy function for component $i$ at $j$ th stage
$E_j$	Enthalpy balance discrepancy function for the $j$ th stage
$S_j$	Fraction of the vapor stream withdrawn from the $j$ th stage
$s_j$	Fraction of the liquid stream withdrawn from the $j$ th stage

#### Greek letters

$\Delta$	difference in variable
$\eta_j$	murphree efficiency of $j$ th stage
$\delta_{ij}$	Kronecker delta function
$\partial$	partial derivative
$\gamma_i$	activity coefficient of component $i$
$\Lambda$	Thermodynamic parameter
$\bar{\alpha}$	P matrix of the Thomas Algorithm
$\bar{\beta}$	q matrix in the Thomas Algorithm

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TABLE 1

CPU time for the inversion of matrix by the proposed method and the Gauss Jordan Elimination

No. of components	CPU time (in Secs.)		Ratio of CPU time (IP/GJ)	Ratio of operation count
	Inversion by partition(I.P)	Gauss Jordan Elimination (GJ)		
5	0.14	0.25	0.56	0.76
10	0.59	1.38	0.43	0.70
15	1.96	5.54	0.35	0.68
20	4.99	16.22	0.31	0.66

TABLE 4

CPU time for two different problems

Problem No.	No. of components	No. of stages	No. of iterations needed	Run No.	CPU in secs.		Ratio of CPU per iteration	
					Normal $t_1$	Symmetry scarcity exploitation $t_2$	$\frac{t_2}{t_1}$	$\frac{t_2}{t_1}$
1	4	20	2	1	7.95	1.95	0.12	0.12
				2	7.93	1.96	0.12	0.12
				3	7.95	1.96	0.12	0.12
2	14	8	5	1	784.64	57.12	0.01	0.01
				2	784.62	57.11	0.01	0.01
				3	784.62	57.14	0.01	0.01

## APPENDIX A

## ELEMENTS OF THE SUBMATRICES

1. FOR IDEAL VLE SYSTEMA. FOR A MATRIX

For  $1 \leq i, j \leq C$  &  $1 \leq n \leq N$

$$\frac{\partial M_{i,n}}{\partial l_{j,n-1}} = \delta_{i,j}, \quad \frac{\partial M_{i,n}}{\partial v_{j,n-1}} = \frac{\partial M_{i,n}}{\partial T_{n-1}} = 0$$

$$\frac{\partial O_{i,n}}{\partial l_{j,n-1}} = \frac{\partial O_{i,n}}{\partial v_{j,n-1}} = \frac{\partial O_{i,n}}{\partial T_{n-1}} = 0$$

$$\frac{\partial E_n}{\partial l_{i,n-1}} = h_{i,n-1}; \quad \frac{\partial E_n}{\partial v_{i,n-1}} = 0$$

$$\frac{\partial E_n}{\partial T_n} = \sum_{i=1}^C l_{i,n-1} \frac{\partial h_{i,n-1}}{\partial T_{n-1}}$$

B. FOR B MATRIX

For  $1 \leq i, j \leq C$  &  $1 \leq n \leq N$

$$\frac{\partial M_{i,n}}{\partial l_{j,n}} = - (1 + s_n) \delta_{ij}$$

$$\frac{\partial M_{i,n}}{\partial v_{j,n}} = - (1 + s_n) \delta_{ij}$$

$$\frac{\partial M_{i,n}}{\partial T_n} = 0$$

Appendix A continued.

$$\frac{\partial^0_{i,n}}{\partial l_{j,n}} = \eta_n k_{i,n} \frac{\delta_{ij} L_n - l_{in}}{L_n^2}$$

$$\frac{\partial^0_{i,n}}{\partial v_{j,n}} = \frac{v_{i,n} - v_n \delta_{ij}}{v_n^2}$$

$$\frac{\partial^0_{i,n}}{\partial T_n} = \eta_n \frac{l_{i,n}}{L_n} \frac{dk_{i,n}}{dT_n}$$

$$\frac{\partial E_n}{\partial l_{i,n}} = - (1 + s_m) h_{i,n}$$

$$\frac{\partial E_n}{\partial v_{i,n}} = - (1 + s_m) H_{i,n}$$

$$\frac{\partial E_n}{\partial T_n} = - \sum_{i=1}^C (1 + s_m) v_{i,n} \frac{dH_{i,n}}{dT_n} - \sum_{i=1}^C (1 + s_n) l_{i,n} \frac{dh_{i,n}}{dT_n}$$

C. FOR  $\bar{O}$  MATRIX

For  $1 \leq i, j \leq C$  &  $1 \leq n \leq N$

$$\frac{\partial M_{i,n}}{\partial l_{j,n+1}} = 0; \quad \frac{\partial M_{i,n}}{\partial v_{j,n+1}} = \delta_{ij}; \quad \frac{\partial M_{i,n}}{\partial T_{n+1}} = 0$$

$$\frac{\partial^0_{i,n}}{\partial l_{j,n+1}} = 0; \quad \frac{\partial^0_{i,n}}{\partial v_{j,n+1}} = (1 - \eta_m) \frac{\delta_{ij} v_{n+1} - v_{i,n+1}}{v_{n+1}^2}$$

Appendix A continued

$$\frac{\partial^0_{i,n}}{\partial T_{n+1}} = 0 = \frac{\partial^{E_n}}{\partial l_{i,n+1}}$$

$$\frac{\partial^{E_n}}{\partial v_{i,n+1}} = H_{i,n+1} \quad ; \quad \frac{\partial^{E_n}}{\partial T_{n+1}} = \sum_{i=1}^c v_{i,n+1} \frac{dH_{i,n+1}}{dT_{n+1}}$$


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APPENDIX B

## SAMPLE PROBLEM No.1

## DATA

## K values

Material	Temperature	
	100°F	200°F
A	500.0	550.0
B	1.50	1.8
C	0.90	1.00
D	$1.0 \times 10^{-6}$	$1.5 \times 10^{-6}$

Molar liquid enthalpies,  $10^3$  cal/mole.

A	0.01	0.013
B	0.30	0.33
C	0.40	0.44
D	1.50	1.90

Molar vapor enthalpies,  $10^3$  cal/mole

A	1.00	1.002
B	1.80	1.82
C	2.00	2.03
D	5.75	5.95

Component	$a_{1i}$	$a_{2i}$	$a_{3i}$	$a_{4i}$
CO <sub>2</sub>	- 0.6282223x10 <sup>-1</sup>	0.30688802x10 <sup>-3</sup>	0.39996468x10 <sup>-6</sup>	-0.57899830x10 <sup>-9</sup>
N <sub>2</sub>	0.50596821	-0.43488364x10 <sup>-3</sup>	-0.15009991x10 <sup>-5</sup>	0.34494154x10 <sup>-8</sup>
CH <sub>4</sub>	0.15584934	-0.15205775x10 <sup>-3</sup>	0.50349212x10 <sup>-6</sup>	-0.17713546x10 <sup>-9</sup>
C <sub>2</sub> H <sub>6</sub>	0.91486037x10 <sup>-1</sup>	-0.16355944x10 <sup>-3</sup>	0.33741924x10 <sup>-6</sup>	0.14797150x10 <sup>-9</sup>
C <sub>3</sub> H <sub>8</sub>	0.37769508x10 <sup>-1</sup>	-0.64491702x10 <sup>-4</sup>	0.29233627x10 <sup>-6</sup>	-0.48597680x10 <sup>-11</sup>
i C <sub>4</sub> H <sub>10</sub>	0.36708355x10 <sup>-1</sup>	-0.94310963x10 <sup>-4</sup>	0.28026648x10 <sup>-6</sup>	0.10462797x10 <sup>-10</sup>
n C <sub>4</sub> H <sub>10</sub>	0.37231278x10 <sup>-1</sup>	-0.13635085x10 <sup>-3</sup>	0.37584653x10 <sup>-6</sup>	-0.69237741x10 <sup>-10</sup>
i C <sub>5</sub> H <sub>12</sub>	0.15414596x10 <sup>-1</sup>	-0.34736106x10 <sup>-4</sup>	0.12591028x10 <sup>-6</sup>	0.73157133x10 <sup>-10</sup>
i C <sub>5</sub> H <sub>12</sub>	0.19747034x10 <sup>-1</sup>	-0.40284984x10 <sup>-4</sup>	0.14439195x10 <sup>-6</sup>	0.56656790x10 <sup>-10</sup>
n C <sub>6</sub> H <sub>14</sub>	0.88765752x10 <sup>-3</sup>	0.37082646x10 <sup>-4</sup>	-0.40746951x10 <sup>-7</sup>	0.15187203x10 <sup>-9</sup>
n C <sub>7</sub> H <sub>16</sub>	0.63677356x10 <sup>-2</sup>	-0.64409760x10 <sup>-5</sup>	0.31793974x10 <sup>-7</sup>	0.78284379x10 <sup>-10</sup>
n C <sub>8</sub> H <sub>18</sub>	0.99674799x10 <sup>-2</sup>	-0.34673591x10 <sup>-4</sup>	0.82305291x10 <sup>-7</sup>	0.21022392x10 <sup>-10</sup>
n C <sub>9</sub> H <sub>20</sub>	0.78793392x10 <sup>-2</sup>	-0.23886125x10 <sup>-4</sup>	0.62435951x10 <sup>-7</sup>	0.25793478x10 <sup>-10</sup>
n C <sub>10</sub> H <sub>22</sub>	0.64146556x10 <sup>-2</sup>	-0.16131104x10 <sup>-4</sup>	0.30005250x10 <sup>-7</sup>	0.30266026x10 <sup>-10</sup>

$$K_i = T (a_{1i} + a_{2i} T + a_{3i} T^2 + a_{4i} T^3) (T \text{ in } ^\circ R)$$

Component	$b_{1i}$	$b_{2i}$	$b_{3i}$	$b_{4i}$
CO <sub>2</sub>	0.22524075x10 <sup>4</sup>	0.5446243x10 <sup>1</sup>	0.2791080x10 <sup>-1</sup>	- 0.18765335x10 <sup>-4</sup>
N <sub>2</sub>	0.15837112x10 <sup>4</sup>	0.3731512x10 <sup>1</sup>	0.17655857x10 <sup>-1</sup>	- 0.14662071x10 <sup>-4</sup>
CH <sub>4</sub>	0.81635181x10 <sup>3</sup>	0.7206460x10 <sup>1</sup>	0.15354034x10 <sup>-1</sup>	- 0.84406456x10 <sup>-5</sup>
C <sub>2</sub> H <sub>6</sub>	0.97404712x10 <sup>3</sup>	0.11454294x10 <sup>2</sup>	0.79399594x10 <sup>-2</sup>	- 0.42183183x10 <sup>-6</sup>
C <sub>3</sub> H <sub>8</sub>	0.21237510x10 <sup>4</sup>	0.46383524x10 <sup>1</sup>	0.31726830x10 <sup>-1</sup>	- 0.12580301x10 <sup>-4</sup>
i C <sub>4</sub> H <sub>10</sub>	0.17543628x10 <sup>4</sup>	0.92456856x10 <sup>1</sup>	0.30206113x10 <sup>-1</sup>	- 0.89584664x10 <sup>-5</sup>
n C <sub>4</sub> H <sub>10</sub>	0.32309192x10 <sup>4</sup>	0.66175545x10 <sup>1</sup>	0.38262386x10 <sup>-1</sup>	- 0.16110935x10 <sup>-4</sup>
i C <sub>5</sub> H <sub>12</sub>	0.33611663x10 <sup>4</sup>	0.39552670x10 <sup>1</sup>	0.54925641x10 <sup>-1</sup>	- 0.25869682x10 <sup>-4</sup>
n C <sub>5</sub> H <sub>12</sub>	0.43454375x10 <sup>4</sup>	0.10596339x10 <sup>2</sup>	0.43731511x10 <sup>-1</sup>	- 0.19637475x10 <sup>-4</sup>
n C <sub>6</sub> H <sub>14</sub>	-0.44150469x10 <sup>4</sup>	0.70354599x10 <sup>2</sup>	-0.67470074x10 <sup>-1</sup>	0.60245657x10 <sup>-4</sup>
n C <sub>7</sub> H <sub>16</sub>	0.66707016x10 <sup>2</sup>	0.18159073x10 <sup>2</sup>	0.38164884x10 <sup>-1</sup>	- 0.42837073x10 <sup>-5</sup>
n C <sub>8</sub> H <sub>18</sub>	-0.10632578x10 <sup>2</sup>	0.19229950x10 <sup>2</sup>	0.40186413x10 <sup>-1</sup>	- 0.70521889x10 <sup>-6</sup>
n C <sub>9</sub> H <sub>20</sub>	-0.79141992x10 <sup>4</sup>	0.81615143x10 <sup>2</sup>	-0.79501927x10 <sup>-1</sup>	0.83943509x10 <sup>-4</sup>
n C <sub>10</sub> H <sub>22</sub>	-0.67810352x10 <sup>4</sup>	0.74108551x10 <sup>2</sup>	-0.58315706x10 <sup>-1</sup>	0.75087155x10 <sup>-4</sup>

$$h_i = b_{1i} + b_{2i}T + b_{3i}T^2 + b_{4i}T^3 \quad (T \text{ in } ^\circ R) \text{ Btu/lb mole.}$$



Component	$C_{1i}$	$C_{2i}$	$C_{3i}$	$C_{4i}$
CO <sub>2</sub>	0.13978977x10 <sup>5</sup>	- 0.96359463x10 <sup>1</sup>	0.38228422x10 <sup>-1</sup>	-0.26870170x10 <sup>-4</sup>
N <sub>2</sub>	0.48638672x10 <sup>4</sup>	- 0.21227379x10 <sup>1</sup>	0.17565668x10 <sup>-1</sup>	-0.11367006x10 <sup>-4</sup>
CH <sub>4</sub>	0.63255430x10 <sup>4</sup>	- 0.20747757x10 <sup>1</sup>	0.18532634x10 <sup>-1</sup>	-0.10630416x10 <sup>-4</sup>
C <sub>2</sub> H <sub>6</sub>	0.10628934x10 <sup>5</sup>	- 0.28718834x10 <sup>1</sup>	0.24877094x10 <sup>-1</sup>	-0.13233222x10 <sup>-4</sup>
C <sub>3</sub> H <sub>8</sub>	0.13954383x10 <sup>5</sup>	- 0.41930256x10 <sup>1</sup>	0.32614145x10 <sup>-1</sup>	-0.15483340x10 <sup>-4</sup>
i C <sub>4</sub> H <sub>10</sub>	0.94088984x10 <sup>4</sup>	0.39262680x10 <sup>2</sup>	-0.55596594x10 <sup>-1</sup>	0.51507392x10 <sup>-4</sup>
n C <sub>4</sub> H <sub>10</sub>	0.57302344x10 <sup>4</sup>	0.75117737x10 <sup>2</sup>	-0.13120884x10 <sup>0</sup>	0.10517908x10 <sup>-3</sup>
i C <sub>5</sub> H <sub>12</sub>	0.83081953x10 <sup>4</sup>	0.75267792x10 <sup>2</sup>	-0.12945843x10 <sup>0</sup>	0.10845697x10 <sup>-3</sup>
n C <sub>5</sub> H <sub>12</sub>	0.12804211x10 <sup>5</sup>	0.61654007x10 <sup>2</sup>	-0.97365201x10 <sup>-1</sup>	0.84398722x10 <sup>-4</sup>
n C <sub>6</sub> H <sub>14</sub>	0.23001684x10 <sup>5</sup>	0.27744919x10 <sup>2</sup>	-0.31545494x10 <sup>-1</sup>	0.49981289x10 <sup>-4</sup>
n C <sub>7</sub> H <sub>16</sub>	0.14876816x10 <sup>5</sup>	0.59342438x10 <sup>2</sup>	-0.81853271x10 <sup>-1</sup>	0.81429855x10 <sup>-4</sup>
n C <sub>8</sub> H <sub>18</sub>	0.32793215x10 <sup>5</sup>	- 0.35040283x10 <sup>2</sup>	0.11162955x10 <sup>0</sup>	-0.42647429x10 <sup>-4</sup>
n C <sub>9</sub> H <sub>20</sub>	0.47024656x10 <sup>5</sup>	- 0.95395035x10 <sup>2</sup>	0.24547529x10 <sup>0</sup>	-0.13209638x10 <sup>-3</sup>
n C <sub>10</sub> H <sub>22</sub>	0.55238211x10 <sup>5</sup>	- 0.13195618x10 <sup>3</sup>	0.32518369x10 <sup>0</sup>	-0.18188384x10 <sup>-3</sup>

$$H_i = C_{1i} T + C_{2i} T^2 + C_{3i} T^3 \quad (T \text{ in } ^\circ R) \text{ Btu/lb mole.}$$

## APPENDIX D

3  
1 2  
4 1 2 3 4 5 6  
1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 22 23 24 25 26 27 28 29 30 31 32 33 34 35 36 37 38 39 40 41 42 43 44 45 46 47 48 49 50 51 52 53 54 55 56 57 58 59 60 61 62 63 64 65 66 67 68 69 70 71 72 73 74 75 76 77 78 79 80 81 82 83 84 85 86 87 88 89 90 91 92 93 94 95 96 97 98 99 100 101 102 103 104 105 106 107 108 109 110 111 112 113 114 115 116 117 118 119 120 121 122 123 124 125 126 127 128 129 130 131 132 133 134 135 136 137 138 139 140 141 142 143 144 145 146 147 148 149 150 151 152 153 154 155 156 157 158 159 160 161 162 163 164 165 166 167 168 169 170 171 172 173 174 175 176 177 178 179 180 181 182 183 184 185 186 187 188 189 190 191 192 193 194 195 196 197 198 199 200 201 202 203 204 205 206 207 208 209 210 211 212 213 214 215 216 217 218 219 220 221 222 223 224 225 226 227 228 229 230 231 232 233 234 235 236 237 238 239 240 241 242 243 244 245 246 247 248 249 250 251 252 253 254 255 256 257 258 259 260 261 262 263 264 265 266 267 268 269 270 271 272 273 274 275 276 277 278 279 280 281 282 283 284 285 286 287 288 289 290 291 292 293 294 295 296 297 298 299 300 301 302 303 304 305 306 307 308 309 310 311 312 313 314 315 316 317 318 319 320 321 322 323 324 325 326 327 328 329 330 331 332 333 334 335 336 337 338 339 340 341 342 343 344 345 346 347 348 349 350 351 352 353 354 355 356 357 358 359 360 361 362 363 364 365 366 367 368 369 370 371 372 373 374 375 376 377 378 379 380 381 382 383 384 385 386 387 388 389 390 391 392 393 394 395 396 397 398 399 400 401 402 403 404 405 406 407 408 409 410 411 412 413 414 415 416 417 418 419 420 421 422 423 424 425 426 427 428 429 430 431 432 433 434 435 436 437 438 439 440 441 442 443 444 445 446 447 448 449 450 451 452 453 454 455 456 457 458 459 460 461 462 463 464 465 466 467 468 469 470 471 472 473 474 475 476 477 478 479 480 481 482 483 484 485 486 487 488 489 490 491 492 493 494 495 496 497 498 499 500 501 502 503 504 505 506 507 508 509 510 511 512 513 514 515 516 517 518 519 520 521 522 523 524 525 526 527 528 529 530 531 532 533 534 535 536 537 538 539 540 541 542 543 544 545 546 547 548 549 550 551 552 553 554 555 556 557 558 559 560 561 562 563 564 565 566 567 568 569 570 571 572 573 574 575 576 577 578 579 580 581 582 583 584 585 586 587 588 589 590 591 592 593 594 595 596 597 598 599 600 601 602 603 604 605 606 607 608 609 610 611 612 613 614 615 616 617 618 619 620 621 622 623 624 625 626 627 628 629 630 631 632 633 634 635 636 637 638 639 640 641 642 643 644 645 646 647 648 649 650 651 652 653 654 655 656 657 658 659 660 661 662 663 664 665 666 667 668 669 670 671 672 673 674 675 676 677 678 679 680 681 682 683 684 685 686 687 688 689 690 691 692 693 694 695 696 697 698 699 700 701 702 703 704 705 706 707 708 709 710 711 712 713 714 715 716 717 718 719 720 721 722 723 724 725 726 727 728 729 730 731 732 733 734 735 736 737 738 739 740 741 742 743 744 745 746 747 748 749 750 751 752 753 754 755 756 757 758 759 760 761 762 763 764 765 766 767 768 769 770 771 772 773 774 775 776 777 778 779 780 781 782 783 784 785 786 787 788 789 790 791 792 793 794 795 796 797 798 799 800 801 802 803 804 805 806 807 808 809 810 811 812 813 814 815 816 817 818 819 820 821 822 823 824 825 826 827 828 829 830 831 832 833 834 835 836 837 838 839 840 841 842 843 844 845 846 847 848 849 850 851 852 853 854 855 856 857 858 859 860 861 862 863 864 865 866 867 868 869 870 871 872 873 874 875 876 877 878 879 880 881 882 883 884 885 886 887 888 889 890 891 892 893 894 895 896 897 898 899 900 901 902 903 904 905 906 907 908 909 910 911 912 913 914 915 916 917 918 919 920 921 922 923 924 925 926 927 928 929 930 931 932 933 934 935 936 937 938 939 940 941 942 943 944 945 946 947 948 949 950 951 952 953 954 955 956 957 958 959 960 961 962 963 964 965 966 967 968 969 970 971 972 973 974 975 976 977 978 979 980 981 982 983 984 985 986 987 988 989 990 991 992 993 994 995 996 997 998 999 1000 1001 1002 1003 1004 1005 1006 1007 1008 1009 1010 1011 1012 1013 1014 1015 1016 1017 1018 1019 1020 1021 1022 1023 1024 1025 1026 1027 1028 1029 1030 1031 1032 1033 1034 1035 103



## Appendix D (continued)

[illegible]

## APPENDIX E

## ELEMENTS OF MATRICES FOR NONIDEAL SYSTEM

For nonideal system only the following elements need to evaluate from different expressions. Following expressions are evaluated using UNIQUAK model. Because of the lack of time and for model independent programme, this feature was not incorporated.

$$\frac{\partial O_{i,n}}{\partial v_{j,n}} = \frac{\sum_{ij} v_n - v_{i,n}}{v_n^2} + \frac{l_{i,n}}{L_n} \frac{\gamma_{i,n}^L}{(\gamma_{i,n}^v)^2} \frac{\partial \gamma_{i,n}^v}{\partial v_{j,n}}$$

$$\frac{\partial O_{i,n}}{\partial l_{i,n}} = - \frac{1}{\gamma_{i,n}^v} \left[ \frac{l_{i,n}}{L_n} \frac{\partial \gamma_{i,n}^L}{\partial l_{j,n}} + \gamma_{i,n}^L \left\{ \frac{\sum_{ij} L_m - l_{i,n}}{L_n^2} \right\} \right]$$

$$\frac{\partial O_{i,n}}{\partial T_n} = - \frac{l_{i,n}}{L_n} \frac{\gamma_{i,n}^v \frac{\partial \gamma_{i,n}^L}{\partial T_n} - \gamma_{i,n}^L \frac{\partial \gamma_{i,n}^v}{\partial T_n}}{(\gamma_{i,n}^v)^2}$$

$$\begin{aligned} \gamma_{i,n}^v = & \text{Exp} \left[ 1 - \frac{r_i v_n}{\sum_k v_{k,n} r_k} + \ln \left( \frac{r_i v_n}{\sum_j v_{j,n} r_j} \right) \right. \\ & - \frac{q_i Z}{2} \left\{ 1 - \frac{r_i}{q_i} \frac{\sum_j v_{j,n} q_j}{\sum_j v_{j,n} r_j} + \ln \left( \frac{r_i}{q_i} \right) \right. \\ & + \ln \left( \frac{\sum_j v_{j,n} q_j}{\sum_j v_{j,n} r_j} \right) + q_i \left\{ 1 - \ln \sum_k \left( \frac{v_{j,n} q_j \Lambda_{ij}}{\sum_k v_{k,n} q_k} \right) \right. \\ & \left. \left. - \sum_k \frac{v_{k,n} q_k \Lambda_{k,i}}{\sum_m v_{m,n} q_m \Lambda_{k,m}} \right\} \right] \end{aligned}$$

Appendix E continued.

Similarly for  $\gamma_{i,n}^L$  where  $v$  is substituted by  $l$

$$\begin{aligned} \frac{\partial \gamma_{i,n}^v}{\partial v_{j,n}} = & \gamma_{i,n}^v \left[ - \frac{r_i \sum_k v_{k,n} r_k - v_n r_j}{\left( \sum_k v_{k,n} r_k \right)^2} + \right. \\ & \frac{\sum_k v_{k,n} r_k - r_j v_n}{r_i v_n \left( \sum_k v_{k,n} r_k \right)} - \frac{Z}{2} q_i \left\{ - \frac{r_i}{q_i} \frac{\left( \sum_k v_{k,n} r_k \right)^{q_j} \left( \sum_k v_{k,n} q_k \right)^r}{\left( \sum_k v_{k,n} r_k \right)^2} \right. \\ & \left. + \frac{q_j \sum_k (v_{k,n} r_k) - r_j \sum_k v_{k,n} q_k}{\left( \sum_k v_{k,n} q_k \right) \left( \sum_k v_{k,n} r_k \right)} \right\} \\ & - q_i \left\{ \frac{\sum_k (v_{k,n} q_k) \sum_m m_j q_m \Lambda_{j,m} - q_j \sum_m q_m \Lambda_{m,i} v_{m,n}}{\sum_m (v_{m,n} q_m \Lambda_{i,m}) \sum_k (v_{k,n} q_k)} \right. \\ & \left. - q_k \Lambda_{ki} \frac{\sum_{kj} (v_{m,n} q_m \Lambda_{k,m}) - v_{k,n} q_j \Lambda_{k,j}}{\left( \sum_m (v_{m,n} q_m \Lambda_{k,m}) \right)^2} \right\} \\ o_{i,n} = & \frac{v_{i,n}}{v_n} - \frac{l_{i,n}}{l_n} \frac{\gamma_{i,n}^L}{\gamma_{i,n}} \end{aligned}$$

$$\Lambda_{j,i} = \exp\left(-\frac{a_{ji}}{RT}\right) \quad \text{where } a_{ji} \text{ are UNIQUAK parameter.}$$

$$\begin{aligned}
\frac{\partial \gamma_{i,n}^v}{\partial T_n} &= \gamma_{i,n}^v \left[ - \frac{q_{ij} \sum_j \frac{\partial \Lambda_{j,i}}{\partial T_n}}{\sum_j o_j \Lambda_{i,j}} - \sum_k \frac{\sum_j o_j \Lambda_{k,j} o_k \frac{\partial \Lambda_{k,j}}{\partial T_n}}{\left( \sum_j o_j \Lambda_{i,j} \right)^2} \right. \\
&\quad \left. - \frac{o_k \Lambda_{k,j} \sum_j o_j \frac{\partial \Lambda_{k,j}}{\partial T_m}}{\left( \sum_j o_j \Lambda_{i,j} \right)^2} \right] \\
&= - \frac{\gamma_{i,n}^v}{RT_m^2} \frac{q_{ij} \sum_j o_j \Lambda_{j,i} |_n}{\sum_j o_j \Lambda_{n,j}} - \\
&\quad \sum_k \frac{\left( \sum_j o_j \Lambda_{k,j} \right) o_k \Lambda_{k,i} |_n - o_k \Lambda_{k,j} \sum_j o_j \Lambda_{k,i} |_n}{\left( \sum_j o_j \Lambda_{i,j} \right)^2}
\end{aligned}$$

GENERAL PROGRAM FOR DESIGN AND SIMULATION OF MULTICOMPONENT  
MULTISTAGE EQUILIBRIUM SEPARATION PROCESSES  
=====

DEVELOPED AND PROGRAMMED BY L. PIENK

=====

EXTENDED NAPHTHALI SANDHOLM METHOD  
SPARSITY AND SYMMETRY EXPLOITATION

=====

LISTING OF SYMBOLS ARE AS FOLLOWS

=====

AL(J): LIO. RATE OF THE J TH STAGE  
V(J): VAP. RATE OF THE J TH STAGE  
SV(J,I): VAP. RATE OF COMPONENT I AT THE J TH STAGE  
SL(J,I): LIO. RATE OF COMPONENT I AT THE J TH STAGE  
SQ(J): HEAT INPUT AT THE J TH STAGE  
SS(J): FRACTION OF VAP. STREAM TAKEN FROM THE J TH STAGE  
SSS(J): FRACTION OF LIO. STREAM TAKEN FROM THE J TH STAGE  
ETA(J): MURPHREE EFFICIENCY OF THE J TH STAGE  
SH(I): LIO. PHASE ENTHALPY OF COMPONENT I AT ANY STAGE  
H(I): VAP. PHASE ENTHALPY OF COMPONENT I AT J TH STAGE  
HF(I): ENTHALPY OF FEED AT ANY STAGE FOR COMPONENT I  
HH(I): ENTHALPY OF COMPONENT I NEXT BOTTOM STAGE OF THE STAGE  
TB : TEMPERATURE OF THE VAPOR ENTERING N TH PLATE  
TO : TEMPERATURE OF THE LIQUID ENTERING INTO FIRST PLATE  
SLO(I) : LIO. RATE OF COMPONENT I ENTERING AT FIRST PLATE  
SVO(I): VAPOR FLOW RATE OF COMPONENT I ENTERING INTO N TH PLATE  
VB : TOTAL VAPOR RATE ENTERING INTO THE N TH PLATE  
UNDER CONSIDERATION  
SHH(I): ENTHALPY OF COMPONENT I NEXT UP. STAGE OF THE STAGE  
UNDER CONSIDERATION  
AK(I): EQUILIBRIUM CONSTANT VALUE FOR COMPONENT I AT ANY STAGE  
N: NUMBER OF STAGES  
C: TOTAL NUMBER OF COMPONENTS INVOLVED FOR SEPARATION  
SF(J,I): FEED RATE OF COMPONENT I AT THE J TH STAGE  
TF(J): FEED TEMPERATURE OF THE J TH STAGE  
Q : ENTHALPY BALNCE NORMALISATION FACTOR

=====

SUBROUTINE ENL : COMPUTES LIQUID PHASE ENTHALPY OF ALL  
COMPONENTS FOR A GIVEN STAGE  
SUBROUTINE ENV : COMPUTES VAPOR PHASE ENTHALPY OF ALL  
COMPONENTS AT A GIVEN STAGE  
..... DIST : COMPUTES THE EQUILIBRIUM CONSTANT FOR ALL  
COMPONENTS AT GIVEN STAGE  
..... DDIST : COMPUTES THE DERIVATIVE OF EQUILIBRIUM  
CONSTANT K W.R.T. TEMPERATURE FOR A STAGE  
..... DENL : COMPUTES THE DERIVATIVE OF THE LIQUID  
PHASE ENTHALPY OF ALL COMPONENTS FOR A  
PARTICULAR STAGE  
..... DENV : COMPUTES THE DERIVATIVE OF THE VAPOR PHASE  
ENTHALPY OF ALL COMPONENTS FOR A PARTICULAR  
STAGE  
..... BI : COMPUTES THE INVERSION OF B SUBMATRIX  
..... BII : COMPUTE INVERSION OF B1 MATRIX  
NEW VECTORS

=====

INTEGER C,CT  
COMMON C,CT,N  
COMMON /AREA1/SLO,SVB,TB,TO,VB/AREA2/SS,SSS,TF,ETA,SQ  
COMMON /A1/SA/A2/SC/A3/SE  
DIMENSION B(29,29),C1(29,29),PB(14),PC(14),C2(8,29,29)



```

1,F(29),F1(8,29),A(29,29),SVB(14),SA(14,4),SE(14,4)
2,SL(8,14),SV(8,14),AL(8),V(8),SS(8),SSS(8),
3,SF(8,14),SH(14),H(14),SO(8),SHH(14),HF(14),TF(8),
4,ETA(8),AK(14),T(8),HH(14),PA(14),SLO(14),
5VO(20),SC(14,4)
=====
OPEN (UNIT=21,FILE='S.DAT')
=====
INPUT TERMS MAINLY GUESS VECTOR AND DATA SPECIFICATION
=====
READ(41,*)N,CT,C
READ(41,*)((SL(J,I),I=1,C),J=1,N)
READ(41,*)((SV(J,I),I=1,C),J=1,N)
READ(41,*)(V(J),J=1,N)
READ(41,*)(AL(J),J=1,N)
READ(41,*)(T(J),J=1,N)
READ(41,*)(TF(J),J=1,N)
READ(41,*)(SO(J),J=1,N)
READ(41,*)(ETA(J),J=1,N)
READ(41,*)(SS(J),J=1,N)
READ(41,*)(SSS(J),J=1,N)
READ(41,*)R,O,EPS
READ(41,*)((SF(J,I),I=1,C),J=1,N)
READ(41,*)(SLO(I),I=1,C)
READ(41,*)(SVB(I),I=1,C)

READ(41,*)TB,TO,VB
READ(41,*)((SA(I,J),J=1,4),I=1,3)
READ(41,*)((SC(I,J),J=1,4),I=1,3)
READ(41,*)((SE(I,J),J=1,4),I=1,3)
=====
END OF INPUT SPECIFICATION
=====
AEF=0.
IF(IN,GE.1)GOTO 701
WRITE(44,2210)
FORMAT(4X,'INITIAL GUESS OF FLOW RATES AND TEMPERATURE ARE:')
WRITE(44,2211)
FORMAT(/,4X,'VAPOR PHASE COMPONENT FLOW RATES ARE')
WRITE(44,2212)
FORMAT(4X,36('-'))
WRITE(44,2213)
FORMAT(4X,'COMPONENT NO.',10X,'STAGE NOS. ARE')
WRITE(44,4415)
FORMAT(4X,13('-'),10X,14('-'),/)
WRITE(44,2214)
FORMAT(20X,'1',12X,'2',12X,'3',12X,'4',12X,'5',12X,'6',14X,
1'7',12X,'8')
WRITE(44,2241)
FORMAT(4X,116('-'))
WRITE(44,4451)
FORMAT(/)
WRITE(44,332)(I,(SV(J,I),J=1,N),I=1,C)
FORMAT((4X,I3,7X,8(E10.4,3X)),/)
WRITE(44,1219)
FORMAT(/,4X,'LIQ. COMP. FLOW RATES ARE')
WRITE(44,2212)
WRITE(44,2213)
WRITE(44,4415)
WRITE(44,2214)
WRITE(44,2241)

```

```

WRITE(44,332)(I,(SL(J,I),J=1,N),I=1,C)
WRITE(44,4440)
FORMAT(//,'INITIAL VAPOR AND LIQUID RATE AND TEMPERATURE GUESS
1 ARE ',//)
WRITE(44,4467)
WRITE(44,4468)
WRITE(44,7979)
WRITE(44,13)(J,V(J),AL(J),T(J),J=1,N)
WRITE(44,6100)
FORMAT(//,20X,'COMPONENT ',6X,'TOP LIQ.FEED',10X,'BOTTOM VAP.FEED
1D. ')
WRITE(44,6101)
FORMAT(20X,10(' '),4X,18(' '),4X,18(' '))
WRITE(44,6102)(I,SL(I),SVB(I),I=1,C)
FORMAT(24X,I3,7X,2(E18.8,4X))/?
FORMAT(27X,'IIT KANPUR INDIA ')
FORMAT(27X,'1984')
WRITE(5,8)
WRITE(5,14)
WRITE(5,15)
FORMAT(/,4X,'DEVELOPED AND PROGRAMMED BY L. FIENK')
=====
# COMPUTATION OF AUGMENTED ERROR FUNCTION AT THE GUESS VECTOR
# =====
# # # CONTRIBUTION DUE TO MASS BALANCE # # #
=====
EVALUATION OF LO(I) & V(N+1,I) FOR TOTAL CONDENSER
& TOTAL REBOILER
=====
O=1./O
END OF CONDENSER & REBOILER PART
IF ENTERING LIQ. AT PLATE 1 IS NOT AT T(1) ADJUST THIS TL
ACCORDINGLY
TL=T(1)
DO 1 J=1,N-1
P1=1.+SS(J)
P2=1.+SSS(J)
IF(J.NE.1) GOTO 78
DO 1111 I=1,C
F1(1,I)=-(SL(I)+SV(J+1,I)+SF(J,I)-P1*SV(J,I)-P2*SL(J,I))
AEF=AEF+F1(1,I)*F1(1,I)
CONTINUE
GOTO 1
DO 105 I=1,C
F1(J,I)=-(SL(J-1,I)+SV(J+1,I)+SF(J,I)-P1*SV(J,I)-P2*SL(J,I))
AEF=AEF+F1(J,I)*F1(J,I)
CONTINUE
CONTINUE
DO 405 I=1,C
F1(N,I)=-(SL(N-1,I)+SVB(I)+SF(N,I)-P1*SV(N,I)-P2*SL(N,I))
AEF=AEF+F1(N,I)*F1(N,I)
CONTINUE
WRITE(44,18)AEF
FORMAT(//,4X,'AEF AFTER MASS BALANCE=',E11.4)
#=====
# END OF EVALUATION OF MASS BALANCE CONTRIBUTION
# =====
# START OF EVALUATION OF THE CONTRIBUTION DUE TO
# ENTHALPY BALNACE
# =====

```

```

=====
E=0
DO 2 J=1,N-1
TT=T(J)
P1=1.+SS(J)
P2=1.+SSS(J)
TFF=TF(J)
CALL ENL(TT,SH)
IF(J.NE.1) GOTO 601
CALL ENV(TT,H)
CALL ENL(TO,SHH)
CALL ENL(TFF,HF)
T2=T(J+1)
CALL ENV(T2,HH)
IF(J.NE.1) GOTO 26
DO 23 I=1,C
E=E+SL(I)*SHH(I)+SV(2,I)*HH(I)+SF(1,I)*HF(I)
1-P2*SL(1,I)*SH(I)-P2*SV(1,I)*H(I)
SHH(I)=SH(I)
H(I)=HH(I)
CONTINUE
F1(1,CT)=(E+SO(1))
AEF=AEF+F1(1,CT)*F1(1,CT)
F1(1,CT)=0*F1(1,CT)
FORMAT(4X,'J=',I3,4X,'AEF OF ENTHALPY =',E11.4)
GO TO 1112
E=0
DO 172 I=1,C
E=E+SL(J-1,I)*SHH(I)+SV(J+1,I)*HH(I)+SF(J,I)*HF(I)
1-P2*SL(J,I)*SH(I)-P1*SV(J,I)*H(I)
SHH(I)=SH(I)
H(I)=HH(I)
CONTINUE
F1(J,CT)=-(E+SO(J))
AEF=AEF+F1(J,CT)*F1(J,CT)
F1(J,CT)=0*F1(J,CT)
WRITE(5,22)J,AEF
CONTINUE
TT=T(N)
TFF=TF(N)
CALL ENL(TT,SH)
CALL ENL(TFF,HF)
CALL ENV(TB,HH)
E=0
DO 272 I=1,C
E=E+SL(N-1,I)*SHH(I)+SVB(I)*HH(I)+SF(N,I)*HF(I)-P2*SL(N,I)*SH(I)
1-P1*SV(N,I)*H(I)
CONTINUE
F1(N,CT)=-(E+SO(N))
AEF=AEF+F1(N,CT)*F1(N,CT)
F1(N,CT)=0*F1(N,CT)
WRITE(44,22)N,AEF
WRITE(5,22)N,AEF
FFF=AEF
=====
# TO COMPUTE THE LIQUID & VAPOR FLOW RATE FOR ALL STAGES
# =====
# CONTRIBUTION DUE TO EQUILIBRIUM CONDITION CONSIDERING
# EFFICIENCY OF ALL STAGES
# =====

```

```

=====
DO 4 J=1,N-1
TT=T(J)
CALL DIST(TT,AK)
DO 4 I=1,C
F1(J,C+I)=- (ETA(J)*AK(I)*SL(J,I)/AL(J)-SV(J,I)/V(J)+(1-ETA(J))*
1SV(J+1,I)/V(J+1))
AEF=AEF+F1(J,C+I)*F1(J,C+I)
CONTINUE
TT=T(N)
CALL DIST(TT,AK)
DO 404 I=1,C
F1(N,C+I)=- (ETA(N)*AK(I)*SL(N,I)/AL(N)-SV(N,I)/V(N)+(1-ETA(N))*
1SVB(I)/VB)
AEF=AEF+F1(N,C+I)*F1(N,C+I)
CONTINUE
=====
#          END OF ERROR FUNCTION EVALUATION
=====
IF(FFF-EPS) 5,5,6
=====
FIND THE DIRECTION OF THE N TH PLATE
TT=T(1)
P1=1.+SS(1)
P2=1.+SSS(1)
CALL DIST(TT,AK)
CALL ENL(TT,SH)
CALL ENV(TT,H)
CALL DDIST(TT,PA)
DO 36 I=1,C
B(C+I,2*C+1)=PA(I)
CONTINUE
CALL DENL(TT,PA)
DO 38 I=1,C
B(I,I)=PA(I)
CONTINUE
CALL DENV(TT,PA)
DO 40 I=1,C
B(I,I+C)=PA(I)
CONTINUE
P3=1./AL(1)
TT=0.
B(CT,CT)=0.
AAL=P3**2
VV=1./V(1)-2
DO 41 I=1,C
B(I+C,2*C+1)=ETA(1)*B(C+I,2*C+1)*P3*SL(1,I)
B(2*C+1,I)=-P2*SH(I)*0
B(2*C+1,C+I)=-P1*H(I)*0
B(2*C+1,2*C+1)=-SV(1,I)*B(I,C+I)+B(2*C+1,2*C+1)
TT=TT-SL(1,I)*B(I,I)
CONTINUE
DO 81 I=1,C
DO 81 IJ=1,C
IF(I.EQ.IJ) GOTO 82
B(I+C,IJ)=-ETA(1)*AK(I)*SL(1,I)*AAL
B(I+C,IJ+C)=SV(1,I)*VV
GOTO 81
B(C+I,IJ)=ETA(1)*AK(I)*(AL(1)-SL(1,I))*AAL
B(C+I,IJ+C)=- (V(1)-SV(1,I))*VV
CONTINUE

```

```

B(2*C+1,2*C+1)=B(2*C+1,2*C+1)*P1+TT*P2
B(CT,CT)=B(CT,CT)*Q
DO 42 I=1,C
B(I,I)=-P2
B(I,C+I)=-P1
CONTINUE
END OF COMPUTATION OF B1
WRITE(5,44)((B(I,J),J=1,2*C+1),I=1,2*C+1)
FORMAT(/,4X,'ELEMENTS OF B MATRIX',/(4X,9(E11.4,3X)))
CALL GBI(B)
WRITE(5,44)((B(I,J),J=1,2*C+1),I=1,2*C+1)
COMPUTATION OF C
TT=T(2)
CALL DENV(TT,PA)
CALL ENV(TT,HH)
P3=1/V(2)-2
C1(CT,CT)=0
DO 112 I=1,C
C1(CT,C+I)=HH(I)*Q
C1(CT,CT)=C1(CT,CT)+SV(2,I)*PA(I)
C1(I,C+I)=1
CONTINUE
DO 83 I=1,C
DO 83 II=1,C
IF(I.EQ.II)GOTO84
C1(I+C,II+C)=(1-ETA(1))*SV(2,I)*P3
GOTO 83
C1(I+C,II+C)=(1-ETA(1))*(V(2)-SV(2,I))*P3
CONTINUE
C1(CT,CT)=C1(CT,CT)*Q
WRITE(5,301)((C1(I,J),J=1,CT),I=1,CT)
FORMAT(/,2X,'ELEMENTS OF C MATRIX',/(4X,9(E11.4,3X)))
WRITE(5,44)((B(I,J),J=1,CT),I=1,CT)
CALL BCMUL(B,C1)
DO 111 I=1,CT
F(I)=F1(1,I)
DO 111 II=1,CT
C2(1,I,II)=C1(I,II)
CONTINUE
WRITE(5,301)((C1(I,J),J=1,CT),I=1,CT)
WRITE(5,305)(F(I),I=1,CT)
FORMAT(/,2X,'ELEMENTS OF ERROR VECTOR',/(4X,9(E13.6,3X)))
CALL MTMUL1(B,F)
DO 110 I=1,CT
F1(1,I)=F(I)
CONTINUE
WRITE(5,305)(F(I),I=1,CT)
START OF 2ND AND ONWORD STAGES

DO 54 J=2,N
P1=1.+SS(J)
P2=1.+SSS(J)
TT=T(J-1)
CALL DENL(TT,H)
AA=0
CALL ENL(TT,SHH)
DO 55 I=1,C
AA=AA+SL(J-1,I)*H(I)
A(CT,I)=SHH(I)*Q
A(I,I)=1
CONTINUE

```

```

A(CT,CT)=AA*Q
END OF COMPUTATION OF ELEMENTS OF A MATRIX
WRITE(5,307)((A(I,IJ),IJ=1,CT),I=1,CT)
FORMAT(/,4X,'ELEMENTS OF A MATRIX',/,(4X,9(E11.4,3X)))
CALL ACMUL(A,C1)
WRITE(5,301)((C1(I,JI),JI=1,CT),I=1,CT)
CALL AFMUL(A,F)
WRITE(5,305)(F(I),I=1,CT)
P3=1./AL(J)
TT=T(J)
DO 201 I=1,CT
DO 201 II=1,CT
B(I,II)=0.
CONTINUE
CALL DIST(TT,AK)
CALL ENL(TT,SH)
CALL ENV(TT,H)
CALL DDIST(TT,PA)
DO 60 I=1,C
B(C+I,CT)=PA(I)
CONTINUE
CALL DENV(TT,PA)
DO 61 I=1,C
B(I,C+I)=PA(I)
CONTINUE
CALL DENL(TT,PA)
DO 63 I=1,C
B(I,I)=PA(I)
CONTINUE
AAL=P3^2
VV=1/V(J)^2
TT=0.
B(CT,CT)=0.
DO 57 I=1,C
DO 57 II=1,C
B(I+C,CT)=ETA(J)*B(C+I,CT)*P3*SL(J,I)
B(CT,I)=-P2*SH(I)*Q
B(CT,C+I)=-P1*H(I)*Q
B(CT,CT)=B(CT,CT)-SV(J,I)*B(I,C+I)
TT=TT-SL(J,I)*B(I,I)
CONTINUE
DO 85 I=1,C
DO 85 II=1,C
IF(I.EQ.II) GOTO 86
B(I+C,II)=-ETA(J)*AK(I)*SL(J,I)*AAL
B(I+C,II+C)=SV(J,I)*VV
GOTO 85
B(C+I,II)=ETA(J)*AK(I)*(AL(J)-SL(J,I))*AAL
B(C+I,II+C)=- (V(J)-SV(J,I))*VV
CONTINUE
B(CT,CT)=B(CT,CT)*P1+TT*P2
B(CT,CT)=B(CT,CT)*Q
DO 58 I=1,C
B(I,I)=-P2
B(I,C+I)=-P1
CONTINUE
WRITE(5,44)((B(I,JI),JI=1,CT),I=1,CT)
CALL SUBMAT(B,C1)
WRITE(5,44)((B(I,JI),JI=1,CT),I=1,CT)
CALL GB1(B)
WRITE(5,44)((B(I,JI),JI=1,CT),I=1,CT)
DO 160 I=1,CT

```

```

DO 160 II=1,CT
A(I,II)=0.
C1(I,II)=0.
CONTINUE
IF(J.EQ.N) GOTO 70
TT=T(J+1)
CALL ENV(TT,HH)
P3=1/V(J+1)2
THESE A ELEMENTS ARE LEMENTS OF C1 SUBMATRIX
DO 56 I=1,C
C1(CT,C+I)=HH(I)*Q
CONTINUE
CALL DENV(TT,PA)
DO 59 I=1,C
A(CT,CT)=SV(J+1,I)*PA(I)+A(CT,CT)
C1(I,I+C)=1.
CONTINUE
C1(CT,CT)=Q*A(CT,CT)
DO 87 I=1,C
DO 87 II=1,C
IF(I.EQ.II) GOTO 88
C1(I+C,II+C)=(1.-ETA(J))*SV(J,I)*P3
C1(I+C,II+C)=(1.-ETA(J))*(V(J+1)-SV(J+1,I))*P3
CONTINUE
WRITE(5,301)((C1(I,JI),JI=1,CT),I=1,CT)
CALL BCMUL(B,C1)
DO 67 III=1,CT
DO 67 II=1,CT
C2(J,III,II)=C1(III,II)
CONTINUE
WRITE(5,301)((C1(I,JI),JI=1,CT),I=1,CT)
DO 69 I=1,CT
F(I)=F1(J,I)-F(I)
CONTINUE
WRITE(5,305)(F(I),I=1,CT)
TYPE*,((B(II,IJ),IJ=1,CT),II=1,CT)
FORMAT(4X,'F VALUES ARE:')
CALL MTMUL1(B,F)
WRITE(5,305)(F(I),I=1,CT)
DO 71 I=1,CT
F1(J,I)=F(I)
DO 71 II=1,CT
A(I,II)=0.
CONTINUE
CONTINUE
DO 72 JJ=1,N-1
J=N-JJ
DO 75 I=1,CT
F(I)=F1(J+1,I)
DO 75 II=1,CT
C1(I,II)=C2(J,I,II)
CONTINUE
WRITE(38,301)((C1(I,JD),JD=1,CT),I=1,CT)
WRITE(38,305)(F(I),I=1,CT)
CALL CFMUL(C1,F)
WRITE(5,305)(F(I),I=1,CT)
DO 76 I=1,CT
F1(J,I)=-F(I)+F1(J,I)
CONTINUE
CONTINUE
EFF=AEF

```

```

DF=-1.
DO 135 J=1,N
DO 136 I=1,C
SL(J,I)=SL(J,I)-DF*F1(J,I)
SV(J,I)=SV(J,I)-DF*F1(J,I+C)
CONTINUE
T(J)=T(J)-DF*F1(J,CT)
CONTINUE
IN=IN+1
WRITE(44,200)IN
FORMAT(/,'ITERATION NUMBER=',I3)
AEF=0.
DO 25 J=1,N
V(J)=0.
AL(J)=0.
CONTINUE
DO 202 I=1,CT
DO 202 II=1,CT
B(I,II)=0.
Ci(I,II)=0.
CONTINUE
DO 371 J=1,N
DO 371 I=1,C
V(J)=V(J)+SV(J,I)
AL(J)=AL(J)+SL(J,I)
CONTINUE
DO 444 J=1,N
CONTINUE
GO TO 16
WRITE(44,9)
FORMAT(/,'SUCESSFUL CONVERGENT')
WRITE(44,20)IN
FORMAT(/,'ITERATION NUMBER=',I3)
WRITE(44,2410)
FORMAT(4X,'FINAL VALUES OF FLOW RATES AND TEMPERATURE ARE:')
WRITE(44,2411)
FORMAT(/,4X,'VAPOR PHASE COMPONENT FLOW RATES ARE')
WRITE(44,2412)
FORMAT(4X,36('-',))
WRITE(44,2413)
FORMAT(4X,'COMPONENT NO.',10X,'STAGE NOS. ARE')
WRITE(44,4315)
FORMAT(4X,13('-',),10X,14('-',),/)
WRITE(44,2414)
FORMAT(20X,'1',12X,'2',12X,'3',12X,'4',12X,'5',12X,'6',12X,
1'7',12X,'8')
WRITE(44,2441)
FORMAT(4X,116('-',))
WRITE(44,4351)
FORMAT(/)
WRITE(44,392)(I,(SV(J,I),J=1,N),I=1,C)
FORMAT(4X,13,7X,8(E10.4,3X)),/)
WRITE(44,1319)
FORMAT(/,4X,'LIQ. COMP. FLOW RATES ARE')
WRITE(44,2412)
WRITE(44,2413)
WRITE(44,4315)
WRITE(44,2414)
WRITE(44,2441)
WRITE(44,392)(I,(SL(J,I),J=1,N),I=1,C)
WRITE(44,4449)

```



```

9 FORMAT(//,4X,'VAPOR AND LIQUID RATE AND TEMPERATURE ARE ',//)
WRITE(44,4467)
7 FORMAT(4X,42('-'))
8 WRITE(44,4468)
9 FORMAT(4X,'STAGE, NUMBER',4X,' VAPOR RATE',4X,' LIQUID
1 RATE',4X,' TEMPERATURE')
WRITE(44,7979)
FORMAT(4X,12('-'),4X,19('-'),4X,17('-'),4X,19('-'),/)
WRITE(44,13)(J,V(J),AL(J),T(J),J=1,N)
FORMAT(8X,13,5X,E19.8,4X,E17.8,4X,E19.8)
IFAIL=1
STOP
END
SUBROUTINE MTMUL2(A,B)
INTEGER C,CT
COMMON C,CT,N
DIMENSION A(CT,CT),B(CT,CT),D(29,29)
DO 1 I=1,CT
DO 1 J=1,CT
DO 1 IJ=1,CT
D(I,J)=D(I,J)+A(I,IJ)*B(IJ,J)
CONTINUE
DO 2 I=1,CT
DO 2 J=1,CT
B(I,J)=D(I,J)
D(I,J)=0.
CONTINUE
RETURN
END
SUBROUTINE MTMUL1(A,B)
INTEGER C,CT
COMMON C,CT,N
DIMENSION A(CT,CT),B(CT),D(29)
DO 1 I=1,CT
DO 1 II=1,CT
D(I)=A(I,II)*B(II)+D(I)
CONTINUE
DO 2 I=1,CT
B(I)=D(I)
D(I)=0.
CONTINUE
RETURN
END
SUBROUTINE ENL(T,EL)
INTEGER C,CT
COMMON C,CT,N
COMMON /A2/SC
DIMENSION EL(C),SC(14,4)
DO 1 I=1,C
EL(I)=SC(I,1)+SCK(I,2)*T+SCK(I,3)*T^2+SCK(I,4)*T^3
CONTINUE
RETURN
END
SUBROUTINE DENL(T,EL)
INTEGER C,CT
COMMON C,CT,N
COMMON /A2/SC
DIMENSION EL(C),SC(14,4)
DO 1 I=1,C
EL(I)=SC(I,2)+2.*SC(I,3)*T+3.*SCK(I,4)*T^2
CONTINUE

```

```

RETURN
END
SUBROUTINE ENV(T,EV)
INTEGER C,CT
COMMON C,CT,N
COMMON /A3/SE
DIMENSION EV(C),SE(14,4)
DO 1 I=1,C
EV(I)=SE(I,1)+SE(I,2)*T+SE(I,3)*T^2+SE(I,4)*T^3
CONTINUE
RETURN
END
SUBROUTINE DENV(T,EV)
INTEGER C,CT
COMMON C,CT,N
COMMON /A3/SE
DIMENSION EV(C),SE(14,4)
DO 1 I=1,C
EV(I)=SE(I,2)+SE(I,3)*2.*T+3.*SE(I,4)*T^2
CONTINUE
RETURN
END
SUBROUTINE SUBMAT(B,C1)
INTEGER C,CT
COMMON C,CT,N
DIMENSION B(CT,CT),C1(CT,CT)
DO 1 I=1,CT
DO 1 J=1,CT
B(I,J)=B(I,J)-C1(I,J)
CONTINUE
RETURN
END
SUBROUTINE DIST(T,AK)
INTEGER C,CT
COMMON C,CT,N
COMMON /A1/SA
DIMENSION AK(C),SA(14,4)
DO 1 I=1,C
AK(I)=T*(SA(I,1)+SA(I,2)*T+SA(I,3)*T^2+SA(I,4)*T^3)^3
CONTINUE
RETURN
END
SUBROUTINE DDIST(T,AK)
INTEGER C,CT
COMMON C,CT,N
COMMON /A1/SA
DIMENSION AK(C),SA(14,4)
DO 1 I=1,C
AK(I)=(SA(I,1)+SA(I,2)*T+SA(I,3)*T^2+SA(I,4)*T^3)^3+3.*T*(
1SA(I,2)+2.*SA(I,3)*T+3.*SA(I,4)*T^2)*(SA(I,1)+SA(I,2)*T
2+SA(I,3)*T^2+SA(I,4)*T^3)^2
CONTINUE
RETURN
END
INVERSION OF GENERAL B MATRIX WITH SPARCITY EXPLOITATION
SUBROUTINE GBI(B)
INTEGER C,CT
COMMON C,CT,N
DIMENSION B(CT,CT),BS(14,14),BS1(14,14),PA(14),PB(14)
DO 1 I=1,C
PA(I)=1./B(I,I)

```

```

CONTINUE
DO 2 I=1,C
DO 2 J=1,C
BS(I,J)=PA(I)*B(I,J+C)
CONTINUE
DO 3 I=1,C
DO 3 J=1,C
DO 3 IJ=1,C
BS1(I,J)=BS1(I,J)+B(I+C,IJ)*BS(IJ,J)
CONTINUE
DO 4 I=1,C
DO 4 J=1,C
BS1(I,J)=B(I+C,J+C)-BS1(I,J)
CONTINUE
CALL FMI(BS1)
DO 5 I=1,C
DO 5 J=1,C
B(I+C,J+C)=BS1(I,J)
BS1(I,J)=B(I+C,J)*PA(J)
B(I,J+C)=0.
B(I+C,J)=0.
CONTINUE
DO 6 I=1,C
DO 6 J=1,C
BS(I,J)=0.
DO 6 IJ=1,C
B(I,J+C)=B(I,J+C)-BS(I,IJ)*B(IJ+C,J+C)
CONTINUE
DO 7 I=1,C
DO 7 J=1,C
BS(I,J)=0.
DO 7 IJ=1,C
B(I+C,J)=B(I+C,J)-B(I+C,C+IJ)*BS1(IJ,J)
B(I,J)=B(I,J)-B(I,IJ+C)*BS1(IJ,J)
CONTINUE
DO 9 I=1,C
BS(I,I)=PA(I)
PA(I)=0.
DO 9 J=1,C
B(I,J)=B(I,J)+BS(I,J)
CONTINUE
DO 10 I=1,C
DO 10 II=1,C
PA(I)=PA(I)+B(I,II)*B(II,CT)+B(I,II+C)*B(II+C,CT)
PB(I)=PB(I)+B(I+C,II)*B(II,CT)+B(I+C,II+C)*B(II+C,CT)
CONTINUE
DO 11 I=1,C
BB=BB+B(CT,I)*PA(I)+B(CT,I+C)*PB(I)
CONTINUE
B(CT,CT)=1./(B(CT,CT)-BB)
DO 12 I=1,C
B(I,CT)=-PA(I)*B(CT,CT)
B(I+C,CT)=-PB(I)*B(CT,CT)
PA(I)=0.
PB(I)=0.
CONTINUE
DO 13 J=1,C
DO 13 II=1,C
PA(J)=PA(J)+B(CT,II)*B(II,J)+B(CT,II+C)*B(II+C,J)
PB(J)=PB(J)+B(CT,II)*B(II,J+C)+B(CT,II+C)*B(II+C,J+C)
CONTINUE

```

```

DO 14 I=1,C
B(CT,I)=-B(CT,CT)*PA(I)
B(CT,I+C)=-B(CT,CT)*PB(I)
CONTINUE
DO 15 I=1,C
DO 15 J=1,C
B(I,J)=B(I,J)-B(I,CT)*PA(J)
B(I,J+C)=B(I,J+C)-B(I,CT)*PB(J)
B(I+C,J)=B(I+C,J)-B(I+C,CT)*PA(J)
B(I+C,J+C)=B(I+C,J+C)-B(I+C,CT)*PB(J)
BS1(I,J)=0.
CONTINUE
BB=0.
DO 22 I=1,C
PB(I)=0.
CONTINUE
RETURN
END
CORRECTED VERSION OF PRODUCT FORM OF INVERSE
A MATRIX IS TO BE INVERTED
INVERTED MATRIX IS TT AS WELL AS A)
=====
SUBROUTINE FMI(A)
INTEGER C,CT
COMMON C,CT,N
DIMENSION A(C,C),TT(14,14),UI(14,14),T(14,14),ETA(14,14)
DO 1 I=1,C
UI(I,I)=1.
DO 1 J=1,C
TT(I,J)=0.
CONTINUE
DO 5 K=1,C
ETA(K,K)=1./A(K,K)
DO 4 I=1,C
IF(I.EQ.K) GOTO 4
ETA(I,K)=-A(I,K)/A(K,K)
CONTINUE
DO 6 I=1,C
ETA(I,K)=ETA(I,K)-UI(I,K)
CONTINUE
DO 7 I=1,C
DO 7 J=1,C
T(I,J)=UI(I,J)+ETA(I,K)*UI(K,J)
CONTINUE
DO 8 I=1,C
DO 8 J=1,C
ETA(I,J)=0.
IF(K.NE.1) GOTO 8
TT(I,J)=T(I,J)
CONTINUE
DO 9 I=1,C
DO 9 J=K,C
DO 9 IJ=1,C
ETA(I,J)=T(I,IJ)*A(IJ,J)+ETA(I,J)
CONTINUE
DO 10 I=1,C
DO 10 J=1,C
A(I,J)=ETA(I,J)
ETA(I,J)=0.
CONTINUE
IF(K.EQ.1) GOTO 5

```

```

DO 11 I=1,C
DO 11 J=1,C
DO 11 IJ=1,C
ETA(I,J)=T(I,IJ)*TT(IJ,J)+ETA(I,J)
CONTINUE
DO 12 I=1,C
DO 12 J=1,C
TT(I,J)=ETA(I,J)
ETA(I,J)=0.
CONTINUE
CONTINUE
DO 14 I=1,C
DO 14 J=1,C
A(I,J)=TT(I,J)
CONTINUE
RETURN
END
INVERSION B1 MATRIX
DURING INVERSION SPARCITY IS EXPLOITED AND COMPUTATIONALLY
FASTER THAN AS USUAL INVERSION
SUBROUTINE B1I(B)
INTEGER C,CT
COMMON C,CT,N
DIMENSION B(CT,CT),SB(14,14),PA(14),PB(14)
DO 1 I=1,C
PA(I)=1./B(I,I)
PB(I)=PA(I)*B(I,I+C)
CONTINUE
DO 2 I=1,C
DO 2 J=1,C
SB(I,J)=B(I+C,J)*PB(J)
SB(I,J)=B(I+C,J+C)-SB(I,J)
CONTINUE
CALL FMI(SB)
DO 3 I=1,C
DO 3 J=1,C
B(I+C,J+C)=SB(I,J)
B(I,J+C)=-PB(I)*SB(I,J)
SB(I,J)=0.
CONTINUE
DO 4 I=1,C
DO 4 J=1,C
B(I+C,J)=-B(I+C,J)*PA(J)
B(I,J)=0.
CONTINUE
DO 16 I=1,C
B(I,I)=PA(I)
DO 16 J=1,C
DO 16 IJ=1,C
SB(I,J)=SB(I,J)+B(I,IJ+C)*B(IJ+C,J)
CONTINUE
DO 17 I=1,C
DO 17 J=1,C
B(I,J)=B(I,J)+SB(I,J)
SB(I,J)=0.
CONTINUE
DO 18 I=1,C
DO 18 J=1,C
DO 18 IJ=1,C
SB(I,J)=SB(I,J)+B(I+C,IJ+C)*B(IJ+C,J)
CONTINUE

```

```

DO 5 I=1,C
PA(I)=0.
PB(I)=0.
DO 5 J=1,C
B(I+C,J)=SB(I,J)
SB(I,J)=0.
CONTINUE
DO 10 I=1,C
DO 10 II=1,C
PA(I)=PA(I)+B(I,II)*B(II,CT)+B(I,II+C)*B(II+C,CT)
PB(I)=PB(I)+B(I+C,II)*B(II,CT)+B(I+C,II+C)*B(II+C,CT)
CONTINUE
DO 11 I=1,C
BB=BB+B(CT,I)*PA(I)+B(CT,I+C)*PB(I)
CONTINUE
B(CT,CT)=1./(B(CT,CT)-BB)
DO 12 I=1,C
B(I,CT)=-PA(I)*B(CT,CT)
B(I+C,CT)=-PB(I)*B(CT,CT)
PA(I)=0.
PB(I)=0.
CONTINUE
DO 13 J=1,C
DO 13 II=1,C
PA(J)=PA(J)+B(CT,II)*B(II,J)+B(CT,II+C)*B(II+C,J)
PB(J)=PB(J)+B(CT,II)*B(II,J+C)+B(CT,II+C)*B(II+C,J+C)
CONTINUE
DO 14 I=1,C
B(CT,I)=-B(CT,CT)*PA(I)
B(CT,I+C)=-B(CT,CT)*PB(I)
CONTINUE
DO 15 I=1,C
DO 15 J=1,C
B(I,J)=B(I,J)-B(I,CT)*PA(J)
B(I,J+C)=B(I,J+C)-B(I,CT)*PB(J)
B(I+C,J)=B(I+C,J)-B(I+C,CT)*PA(J)
B(I+C,J+C)=B(I+C,J+C)-B(I+C,CT)*PB(J)
CONTINUE
BB=0.
RETURN
END
SUBROUTINE ACMUL(A,C1)
INTEGER C,CT
COMMON C,CT,N
DIMENSION A(CT,CT),C1(CT,CT)
DO 1 I=1,C
DO 1 J=1,C+1
C1(I+C,J+C)=0.
CONTINUE
DO 3 I=1,C
DO 2 J=1,C
C1(1,I)=C1(1,I)+A(CT,J)*C1(J,I+C)
CONTINUE
C1(CT,C+1)=C1(1,I)+A(CT,CT)*C1(CT,I+C)
C1(1,I)=0.
AA=AA+A(CT,I)*C1(I,CT)
CONTINUE
C1(CT,CT)=AA+A(CT,CT)*C1(CT,CT)
AA=0.
RETURN
END

```

```

SUBROUTINE AFMUL(A,F)
  INTEGER C,CT
  COMMON C,CT,N
  DIMENSION A(CT,CT),F(CT)
  DO 1 I=1,C
    F(C+I)=0
    AA=AA+A(CT,I)*F(I)
  CONTINUE
  F(CT)=AA+F(CT)*A(CT,CT)
  AA=0
  RETURN
END
SUBROUTINE BCMUL(B,C1)
  INTEGER C,CT
  COMMON C,CT,N
  DIMENSION B(CT,CT),C1(CT,CT)
  DO 2 I=1,CT
    DO 2 J=1,CT
      DO 2 K=1,CT
        C1(I,J)=C1(I,J)+B(I,K)*C1(K,J+CD)
      CONTINUE
    DO 1 I=1,CT
      DO 1 J=1,C
        C1(I,J+CD)=C1(I,J)
        C1(I,J)=0
      CONTINUE
    DO 4 I=1,CT
      DO 4 K=1,CT
        C1(I,1)=C1(I,1)+B(I,K)*C1(K,CT)
      CONTINUE
    DO 3 I=1,CT
      C1(I,CT)=C1(I,1)
      C1(I,1)=0
    CONTINUE
  RETURN
END
SUBROUTINE CFMUL(C1,F)
  INTEGER C,CT
  COMMON C,CT,N
  DIMENSION C1(CT,CT),F(CT)
  DO 1 I=1,CT
    DO 1 K=1,C+1
      C1(I,1)=C1(I,1)+C1(I,K+CD)*F(C+K)
    CONTINUE
  DO 2 I=1,CT
    F(I)=C1(I,1)
    C1(I,1)=0
  CONTINUE
  RETURN
END

```

# INPUT SPECIFICATION OF PROBLEM NUMBER 1

```

20 1 1
.18E-02 .3E-01 .27E-03 .96
.17E-02 .6E-01 .62E-03 .93
.16E-02 .77E-01 .1E-02 .91
.15E-02 .88E-01 .16E-02 .9
.15E-02 .94E-01 .22E-02 .9
.15E-02 .98E-01 .31E-02 .89
.15E-02 .1 .4E-02 .89
.15E-02 .1 .55E-02 .89
.15E-02 .1 .7E-02 .88
.15E-02 .1 .92E-02 .88
.15E-02 .1 .11E-01 .88
.15E-02 .1 .15E-01 .88
.14E-02 .1 .19E-01 .87
.14E-02 .99E-01 .23E-01 .87
.14E-02 .98E-01 .29E-01 .87
.14E-02 .96E-01 .37E-01 .86
.14E-02 .94E-01 .45E-01 .85
.14E-02 .91E-01 .56E-01 .85
.14E-02 .88E-01 .68E-01 .84
.138E-02 .85E-01 .82E-01 .83
.79E+02 .83E+02 .86E+02 .88E+02 .89E+02 .9E+02 .91E+02
.91E+02 .91E+02 .92E+02 .92E+02 .92E+02 .92E+02 .93E+02
.93E+02 .94E+02 .95E+02 .96E+02 .97E+02 .98E+02
.1E+03 .1E+03 .1E+03 .1E+03 .1E+03 .1E+03 .1E+03
.11E+03 .11E+03 .11E+03 .11E+03 .11E+03 .11E+03 .11E+03
.11E+03 .11E+03 .11E+03 .11E+03 .11E+03 .11E+03
.125 157. 158. 159. 160. 163. 166. 170. 173. 176.
179. 182. 185. 188. 191. 194. 197. 200.
125. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 200.
1. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1. 1.
0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0.
0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0.
5. 1. 1E-5
0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0.
0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0.
0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0.
0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0. 0.
1. 1. 1E-5 5.75
1.002 1.02 2.03 5.95
0.01 0.3 4 1.5
0.013 .33 .44 1.9
500. 1.5 0.0 1E-6
550. 1.2 1. 1.5E-5
0. 0. 0. 100.
75. 15. 10. 0.
200. 125. 100.

```



GENERAL PROGRAM FOR DESIGN AND SIMULATION OF MULTICOMPONENT  
MULTISTAGE EQUILIBRIUM SEPARATION PROCESSES

PROGRAMMED BY L. FIENK

NAPHTHALI SANDHOLM METHOD

LISTING OF SYMBOLS ARE AS FOLLOWS

AL(J): LIO. RATE OF THE J TH STAGE  
V(J): VAP. RATE OF THE J TH STAGE  
SV(J,I): VAP. RATE OF COMPONENT I AT THE J TH STAGE  
SL(J,I): LIO. RATE OF COMPONENT I AT THE J TH STAGE  
SQ(J): HEAT INPUT AT THE J TH STAGE  
SS(J): FRACTION OF VAP. STREAM TAKEN FROM THE J TH STAGE  
SSS(J): FRACTION OF LIO STREAM TAKEN FROM THE J TH STAGE  
ETA(J): MURPHREE EFFICIENCY OF THE J TH STAGE  
SH(I): LIO PHASE ENTHALPY OF COMPONENT I AT ANY STAGE  
HF(I): VAP. PHASE ENTHALPY OF COMPONENT I AT J TH STAGE  
HH(I): ENTHALPY OF FEED AT ANY STAGE FOR COMPONENT I  
HH(I): ENTHALPY OF COMPONENT I NEXT BOTTOM STAGE OF THE STAGE  
TB : TEMPERATURE OF THE VAPOR ENTERING N TH PLATE  
TD : TEMPERATURE OF THE LIQUID ENTERING INTO FIRST PLATE  
SLO(I) : LIO. RATE OF COMPONENT I ENTERING AT FIRST PLATE  
SVO(I): VAPOR FLOW RATE OF COMPONENT I ENTERING INTO N TH PLATE  
VB : TOTAL VAPOR RATE ENTERING INTO THE N TH PLATE  
UNDER CONSIDERATION  
SHH(I): ENTHALPY OF COMPONENT I NEXT UP STAGE OF THE STAGE  
UNDER CONSIDERATION  
AK(I): EQUILIBRIUM CONSTANT VALUE FOR COMPONENT I AT ANY STAGE  
N: NUMBER OF STAGES  
C: TOTAL NUMBER OF COMPONENTS INVOLVED FOR SEPARATION  
SF(J,I): FEED RATE OF COMPONENT I AT THE J TH STAGE  
TF(J): FEED TEMPERATURE OF THE J TH STAGE  
Q : ENTHALPY BALNCE NORMALISATION FACTOR

SUBROUTINE ENL : COMPUTES LIQUID PHASE ENTHALPY OF ALL  
COMPONENTS FOR A GIVEN STAGE  
SUBROUTINE ENV : COMPUTES VAPOR PHASE ENTHALPY OF ALL  
COMPONENTS AT A GIVEN STAGE  
..... DIST : COMPUTES THE EQUILIBRIUM CONSTANT FOR ALL  
COMPONENTS AT GIVEN STAGE  
..... DDIST : COMPUTES THE DERIVATIVE OF EQUILIBRIUM  
CONSTANT K W.R.T. TEMPERATURE FOR A STAGE  
..... DENL : COMPUTES THE DERIVATIVE OF THE LIQUID  
PHASE ENTHALPY OF ALL COMPONENTS FOR A  
PARTICULAR STAGE  
..... DENV : COMPUTES THE DERIVATIVE OF THE VAPOR PHASE  
ENTHALPY OF ALL COMPONENTS FOR A PARTICULAR  
STAGE  
..... BI : COMPUTES THE INVERSION OF B SUBMATRIX  
..... BII : COMPUTE INVERSION OF B1 MATRIX  
NEW VECTORS

INTEGER C,CT  
COMMON C,CT,N  
COMMON /AREA1/SLO,SVB,TB,TD,VB/AREA2/SS,SSS,TF,ETA,SQ  
COMMON /A1/SA/A2/SC/A3/SE  
DIMENSION B(29,29),C1(29,29),PB(14),PC(14),C2(8,29,29)

```

1, F(29), F1(8, 29), A(29, 29), SVB(14), SA(14, 4), SE(14, 4)
2, SL(8, 14), SV(8, 14), AL(8), V(8), SS(8), SSS(8),
3SF(8, 14), SH(14), H(14), SQ(8), SHH(14), HF(14), TF(8),
4ETA(8), AK(14), T(8), HH(14), PA(14), SLO(14),
5VD(20), SC(14, 4)
=====
OPEN (UNIT=21, FILE='S.DAT')
=====
INPUT TERMS MAINLY GUESS VECTOR AND DATA SPECIFICATION
=====
READ(41, *) N, CT, C
READ(41, *) ((SL(J, I), I=1, C), J=1, N)
READ(41, *) ((SV(J, I), I=1, C), J=1, N)
READ(41, *) (V(J), J=1, N)
READ(41, *) (AL(J), J=1, N)
READ(41, *) (T(J), J=1, N)
READ(41, *) (TF(J), J=1, N)
READ(41, *) (SQ(J), J=1, N)
READ(41, *) (ETA(J), J=1, N)
READ(41, *) (SS(J), J=1, N)
READ(41, *) (SSS(J), J=1, N)
READ(41, *) R, O, EPS
READ(41, *) ((SF(J, I), I=1, C), J=1, N)
READ(41, *) (SLO(I), I=1, C)
READ(41, *) (SVB(I), I=1, C)

READ(41, *) TB, TO, VB
READ(41, *) ((SA(I, J), J=1, 4), I=1, C)
READ(41, *) ((SC(I, J), J=1, 4), I=1, C)
READ(41, *) ((SE(I, J), J=1, 4), I=1, C)
=====
END OF INPUT SPECIFICATION
=====
AEF=0.
IF(IN, GE, 1) GOTO 701
WRITE(44, 2210)
FORMAT(4X, 'INITIAL GUESS OF FLOW RATES AND TEMPERATURE ARE:')
WRITE(44, 2211)
FORMAT(4X, 'VAPOR PHASE COMPONENT FLOW RATES ARE')
WRITE(44, 2212)
FORMAT(4X, 36('-', ' '))
WRITE(44, 2213)
FORMAT(4X, 'COMPONENT NO.', 10X, 'STAGE NOS. ARE')
WRITE(44, 4415)
FORMAT(4X, 13('-', ' '), 10X, 14('-', ' '), /)
WRITE(44, 2214)
FORMAT(20X, '1', 12X, '2', 12X, '3', 12X, '4', 12X, '5', 12X, '6', 12X,
1'7', 12X, '8')
WRITE(44, 2241)
FORMAT(4X, 116('-', ' '))
WRITE(44, 4451)
FORMAT(/)
WRITE(44, 332) (I, (SV(J, I), J=1, N), I=1, C)
FORMAT(4X, 13, 7X, 8(E10.4, 3X)), /)
WRITE(44, 1219)
FORMAT(/, 4X, 'LIQ. COMP. FLOW RATES ARE')
WRITE(44, 2212)
WRITE(44, 2213)
WRITE(44, 4415)
WRITE(44, 2214)
WRITE(44, 2241)
WRITE(44, 332) (I, (SL(J, I), J=1, N), I=1, C)
WRITE(44, 4440)

```

```

40 FORMAT(//,'INITIAL VAPOR AND LIQUID RATE AND TEMPERATURE GUESS
1 ARE ',//)
WRITE(44,4467)
WRITE(44,4468)
WRITE(44,7979)
WRITE(44,13)(J,V(J),AL(J),T(J),J=1,N)
WRITE(44,6100)
00. FORMAT(//,20X,'COMPONENT ',6X,'TOP LIQ.FEED',10X,'BOTTOM VAP.FEE
19. ')
WRITE(44,6101)
01. FORMAT(20X,10(' '),4X,18(' '),4X,18(' '))
02. WRITE(44,6102)(I,SLO(I),SVB(I),I=1,C)
FORMAT((24X,13,7X,2(E18.8,4X)))/)
FORMAT(27X,'TIT KANPUR INDIA ')
FORMAT(27X,'1984')
WRITE(5,8)
WRITE(5,14)
WRITE(5,15)
FORMAT(/,4X,'DEVELOPED AND PROGRAMMED BY L. FIENK')
=====
# COMPUTATION OF AUGMENTED ERROR FUNCTION AT THE GUESS VECTOR
# =====
# # # CONTRIBUTION DUE TO MASS BALANCE # # #
-----
=====
EVALUATION OF LO(I) & V(N+1,I) FOR TOTAL CONDENSER
& TOTAL REBOILER
=====
Q=1.
Q=1./Q
END OF CONDENSER & REBOILER PART
IF ENTERING LIQ. AT PLATE 1 IS NOT AT T(1) ADJUST THIS TL
ACCORDINGLY
TL=T(1)
T(N+1)=T(N)
DO 1 J=1,N-1
P1=1.+SS(J)
P2=1.+SSS(J)
IF(J.NE.1) GOTO 78
DO 1111 I=1,C
F1(1,I)=-(SLO(I)+SV(J+1,I)+SF(J,I)-P1*SV(J,I)-P2*SL(J,I))
AEF=AEF+F1(1,I)*F1(1,I)
FORMAT(4X,'AEF AFTER MASS BALANCE=',E11.4)
CONTINUE
GOTO 1
DO 105 I=1,C
F1(J,I)=-(SL(J-1,I)+SV(J+1,I)+SF(J,I)-P1*SV(J,I)-P2*SL(J,I))
AEF=AEF+F1(J,I)*F1(J,I)
CONTINUE
CONTINUE
DO 405 I=1,C
F1(N,I)=-(SL(N-1,I)+SVB(I)+SF(N,I)-P1*SV(N,I)-P2*SL(N,I))
AEF=AEF+F1(N,I)*F1(N,I)
CONTINUE
WRITE(44,18)AEF
#=====
# END OF EVALUATION OF MASS BALANCE CONTRIBUTION
# =====
# START OF EVALUATION OF THE CONTRIBUTION DUE TO
# ENTHALPY BALNACE
# =====

```

```

=====
E=0
DO 2 J=1,N-1
TT=T(J)
P1=1.+SS(J)
P2=1.+SSS(J)
TFF=TF(J)
CALL ENL(TT,SH)
IF(J.NE.1) GOTO 601
CALL ENV(TT,H)
CALL ENL(TO,SHH)
CALL ENL(TFF,HF)
T2=T(J+1)
CALL ENV(T2,HH)
IF(J.NE.1) GOTO 26
DO 23 I=1,C
E=E+SL(I)*SHH(I)+SV(2,I)*HH(I)+SF(1,I)*HF(I)
1-P2*SL(1,I)*SH(I)-P2*SV(1,I)*H(I)
SHH(I)=SH(I)
H(I)=HH(I)
CONTINUE
F1(1,CT)=(E+SO(1))
AEF=AEF+F1(1,CT)*F1(1,CT)
F1(1,CT)=0*F1(1,CT)
FORMAT(4X,'J=',I3,4X,'AEF OF ENTHALPY =',E11.4)
GO TO 1112
E=0
DO 172 I=1,C
E=E+SL(J-1,I)*SHH(I)+SV(J+1,I)*HH(I)+SF(J,I)*HF(I)
1-P2*SL(J,I)*SH(I)-P1*SV(J,I)*H(I)
SHH(I)=SH(I)
H(I)=HH(I)
CONTINUE
F1(J,CT)=-(E+SO(J))
AEF=AEF+F1(J,CT)*F1(J,CT)
F1(J,CT)=0*F1(J,CT)
WRITE(5,22)J,AEF
CONTINUE
TT=T(N)
TFF=TF(N)
CALL ENL(TT,SH)
CALL ENL(TFF,HF)
CALL ENV(TB,HH)
E=0
DO 272 I=1,C
E=E+SL(N-1,I)*SHH(I)+SVB(I)*HH(I)+SF(N,I)*HF(I)-P2*SL(N,I)*SH(I)
1-P1*SV(N,I)*H(I)
CONTINUE
F1(N,CT)=-(E+SO(N))
AEF=AEF+F1(N,CT)*F1(N,CT)
F1(N,CT)=0*F1(N,CT)
FFF=AEF
WRITE(44,22)N,AEF
WRITE(5,22)N,AEF
=====
# TO COMPUTE THE LIQUID & VAPOR FLOW RATE FOR ALL STAGES
#
# CONTRIBUTION DUE TO EQUILIBRIUM CONDITION CONSIDERING
# EFFICIENCY OF ALL STAGES
#
=====

```

```

DO 4 J=1,N-1
TT=T(J)
CALL DIST(TT,AK)
DO 4 I=1,C
F1(J,C+I)=- (ETA(J)*AK(I)*SL(J,I)/AL(J)-SV(J,I)/V(J)+(1-ETA(J))*
1SV(J+1,I)/V(J+1))
AEF=AEF+F1(J,C+I)*F1(J,C+I)
CONTINUE
TT=T(N)
CALL DIST(TT,AK)
DO 404 I=1,C
F1(N,C+I)=- (ETA(N)*AK(I)*SL(N,I)/AL(N)-SV(N,I)/V(N)+(1-ETA(N))*
1SVB(I)/VB)
AEF=AEF+F1(N,C+I)*F1(N,C+I)
CONTINUE
=====
#          END OF ERROR FUNCTION EVALUATION
=====
IF(FFF-EPS) 5,5,6
=====
FIND THE DIRECTION OF THE N TH PLATE
TT=T(1)
P1=1.+SS(1)
P2=1.+SSS(1)
CALL DIST(TT,AK)
CALL ENL(TT,SH)
CALL ENV(TT,H)
CALL ODIST(TT,PA)
DO 36 I=1,C
B(C+I,2*C+1)=PA(I)
CONTINUE
CALL DENL(TT,PA)
DO 38 I=1,C
B(I,I)=PA(I)
CONTINUE
CALL DENV(TT,PA)
DO 40 I=1,C
B(I,I+C)=PA(I)
CONTINUE
P3=1./AL(1)
TT=0.
B(CT,CT)=0.
AAL=P3-2
VV=1./V(1)-2
DO 41 I=1,C
B(I+C,2*C+1)=ETA(1)*B(C+I,2*C+1)*P3*SL(1,I)
B(2*C+1,I)=-P2*SH(I)*0
B(2*C+1,C+I)=-P1*H(I)*0
B(2*C+1,2*C+1)=-SV(1,I)*B(I,C+I)+B(2*C+1,2*C+1)
TT=TT-SL(1,I)*B(I,I)
CONTINUE
DO 81 I=1,C
DO 81 IJ=1,C
IF(I.EQ.IJ) GOTO 82
B(I+C,IJ)=-ETA(1)*AK(I)*SL(1,I)*AAL
B(I+C,IJ+C)=SV(1,I)*VV
GOTO 81
B(C+I,IJ)=ETA(1)*AK(I)*(AL(1)-SL(1,I))*AAL
B(C+I,IJ+C)=- (V(1)-SV(1,I))*VV
CONTINUE
B(2*C+1,2*C+1)=B(2*C+1,2*C+1)*P1+TT*P2

```

```

B(CT,CT)=B(CT,CT)*Q
DO 42 I=1,C
B(I,I)=-P2
B(I,C+I)=-P1
CONTINUE
END OF COMPUTATION OF B1
WRITE(5,44)((B(I,J),J=1,2*C+1),I=1,2*C+1)
FORMAT(/,4X,'ELEMENTS OF B MATRIX',/(4X,9(E11.4,3X)))
CALL GBI(B)
WRITE(5,44)((B(I,J),J=1,2*C+1),I=1,2*C+1)
COMPUTATION OF C
TT=T(2)
CALL DENV(TT,PA)
CALL ENV(TT,HH)
P3=1/V(2)*2
C1(CT,CT)=0
DO 83 I=1,C
C1(CT,C+I)=HH(I)*Q
C1(CT,CT)=C1(CT,CT)+SV(2,I)*PA(I)
C1(I,C+I)=1
CONTINUE
DO 83 I=1,C
DO 83 II=1,C
IF(I.EQ.II)GOTO84
C1(I+C,II+C)=(1-ETA(1))*SV(2,I)*P3
GOTO 83
C1(I+C,II+C)=(1-ETA(1))*(V(2)-SV(2,I))*P3
CONTINUE
C1(CT,CT)=C1(CT,CT)*Q
WRITE(5,301)((C1(I,J),J=1,CT),I=1,CT)
FORMAT(/,2X,'ELEMENTS OF C MATRIX',/(4X,9(E11.4,3X)))
WRITE(5,44)((B(I,J),J=1,CT),I=1,CT)
CALL MTMUL2(B,C1)
DO 111 I=1,CT
F(I)=F1(1,I)
DO 111 II=1,CT
C2(1,I,II)=C1(I,II)
CONTINUE
WRITE(5,301)((C1(I,J),J=1,CT),I=1,CT)
WRITE(5,305)(F(I),I=1,CT)
FORMAT(/,2X,'ELEMENTS OF ERROR VECTOR',/(4X,9(E13.6,3X)))
CALL MTMUL1(B,F)
DO 110 I=1,CT
F1(1,I)=F(I)
CONTINUE
WRITE(5,305)(F(I),I=1,CT)
START OF 2ND AND ONWORD STAGES
DO 54 J=2,N
P1=1.+SS(J)
P2=1.+SSS(J)
TT=T(J-1)
CALL DENL(TT,H)
AA=0
CALL ENL(TT,SHH)
DO 55 I=1,C
AA=AA+SL(J-1,I)*H(I)
A(CT,I)=SHH(I)*Q
A(I,I)=1
CONTINUE
A(CT,CT)=AA*Q

```



```

END OF COMPUTATION OF ELEMENTS OF A MATRIX
WRITE(5,307)((A(I,IJ),IJ=1,CT),I=1,CT)
FORMAT(/,4X,'ELEMENTS OF A MATRIX',/,(4X,9(E11.4,3X)))
CALL MTMUL2(A,C1)
WRITE(5,301)((C1(I,JI),JI=1,CT),I=1,CT)
CALL MTMUL1(A,F)
WRITE(5,305)(F(I),I=1,CT)
P3=1/V(J)
TT=T(J)
DO 201 I=1,CT
DO 201 II=1,CT
B(I,II)=0.
CONTINUE
CALL DIST(TT,AK)
CALL ENL(TT,SH)
CALL ENV(TT,H)
CALL DDIST(TT,PA)
DO 60 I=1,C
B(C+I,CT)=PA(I)
CONTINUE
CALL DENV(TT,PA)
DO 61 I=1,C
B(I,C+I)=PA(I)
CONTINUE
CALL DENL(TT,PA)
DO 63 I=1,C
B(I,I)=PA(I)
CONTINUE
AAL=P3^2
VV=1/V(J)^2
TT=0.
B(CT,CT)=0.
DO 57 I=1,C
B(I+CT,CT)=ETA(J)*B(C+I,CT)*P3*SL(J,I)
B(CT,I)=-P2*SH(I)*0
B(CT,C+I)=-P1*H(I)*0
B(CT,CT)=B(CT,CT)-SV(J,I)*B(I,C+I)
TT=TT-SL(J,I)*B(I,I)
CONTINUE
DO 85 I=1,C
DO 85 II=1,C
IF(I.EQ.II) GOTO 86
B(I+CT,II)=-ETA(J)*AK(I)*SL(J,I)*AAL

```

```

B(I+C,II+C)=SV(J,I)*VV
GOTO 85
B(C+I,II)=ETA(J)*AK(I)*(AL(J)-SL(J,I))*AAL
B(C+I,II+C)=-(V(J)-SV(J,I))*VV
CONTINUE
B(CT,CT)=B(CT,CT)*P1+TT*P2
B(CT,CT)=B(CT,CT)*Q
DO 58 I=1,C
B(I,I)=-P2
B(I,C+I)=-P1
CONTINUE
WRITE(5,44)((B(I,JI),JI=1,CT),I=1,CT)
CALL SUBMAT(B,C1)
WRITE(5,44)((B(I,JI),JI=1,CT),I=1,CT)
CALL GBF(B)
WRITE(5,44)((B(I,JI),JI=1,CT),I=1,CT)
DO 160 I=1,CT
DO 160 II=1,CT
A(I,II)=0.
C1(I,II)=0.
CONTINUE
IF(J.EQ.N) GOTO 70
TT=T(J+1)
CALL ENV(TT,HH)
P3=1/V(J+1)2
THESE A ELEMENTS ARE LEMENTS OF C1 SUBMATRIX
DO 56 I=1,C
C1(CT,C+I)=HH(I)*Q
CONTINUE
CALL DENV(TT,PA)
DO 59 I=1,C
A(CT,CT)=SV(J+1,I)*PA(I)+A(CT,CT)
C1(I,I+C)=1.
CONTINUE
C1(CT,CT)=Q*A(CT,CT)
DO 87 I=1,C
DO 87 II=1,C
IF(I.EQ.II) GOTO 88
C1(I+C,II+C)=(1.-ETA(J))*SV(J,I)*P3
C1(I+C,II+C)=(1.-ETA(J))*(V(J+1)-SV(J+1,I))*P3
CONTINUE
WRITE(5,301)((C1(I,JI),JI=1,CT),I=1,CT)
CALL MTMUL2(B,C1)
DO 67 III=1,CT
DO 67 II=1,CT
C2(J,III,II)=C1(III,II)
CONTINUE
WRITE(5,301)((C1(I,JI),JI=1,CT),I=1,CT)
DO 69 I=1,CT
F(I)=F1(J,I)-F(I)
CONTINUE
WRITE(5,305)(F(I),I=1,CT)
TYPE* ((B(II,IJ),IJ=1,CT),II=1,CT)
CALL MTMUL1(B,F)
WRITE(5,305)(F(I),I=1,CT)
DO 71 I=1,CT
F1(J,I)=F(I)
DO 71 II=1,CT
A(I,II)=0.
CONTINUE
CONTINUE

```



```

DO 72 JJ=1,N-1
J=N-JJ
DO 75 I=1,CT
F(I)=F1(J+1,I)
DO 75 II=1,CT
C1(I,II)=C2(J,I,II)
CONTINUE
WRITE(38,305)(F(I),I=1,CT)
CALL MTMUL1(C1,F)
WRITE(5,305)(F(I),I=1,CT)
DO 76 I=1,CT
F1(J,I)=-F(I)+F1(J,I)
CONTINUE
CONTINUE
EFF=AEF
OF=-1.
DO 135 J=1,N
DO 136 I=1,C
SL(J,I)=SL(J,I)-OF*F1(J,I)
SV(J,I)=SV(J,I)-OF*F1(J,I+C)
CONTINUE
T(J)=T(J)-OF*F1(J,CT)
CONTINUE
IN=IN+1
WRITE(44,200)IN
FORMAT(/,'ITERATION NUMBER=',I3)
AEF=0.
DO 25 J=1,N
V(J)=0.
AL(J)=0.
CONTINUE
DO 202 I=1,CT
DO 202 II=1,CT
B(I,II)=0.
C1(I,II)=0.
CONTINUE
DO 371 J=1,N
DO 371 I=1,C
V(J)=V(J)+SV(J,I)
AL(J)=AL(J)+SL(J,I)
CONTINUE
DO 444 J=1,N
CONTINUE
GO TO 16
WRITE(44,9)
FORMAT(/,'SUCESSFUL CDNVERGENT')
WRITE(44,20)IN
FORMAT(/,'ITERATION NUMBER=',I3)
WRITE(44,2410)
FORMAT(4X,'FINAL VALUES OF FLOW RATES AND TEMPERATURE ARE:')
WRITE(44,2411)
FORMAT(/,4X,'VAPOR PHASE COMPONENT FLOW RATES ARE')
WRITE(44,2412)
FORMAT(4X,36('-',))
WRITE(44,2413)
FORMAT(4X,'COMPONENT NO.',10X,'STAGE NOS. ARE')
WRITE(44,4315)
FORMAT(4X,13('-',),10X,14('-',),/)
WRITE(44,2414)
FORMAT(20X,'1',12X,'2',12X,'3',12X,'4',12X,'5',12X,'6',12X,
1'7',12X,'8')

```

```

141 WRITE(44,2441)
151 FORMAT(4X,116(' - '))
162 WRITE(44,4351)
172 FORMAT(//)
182 WRITE(44,392)(I,(SV(J,I),J=1,N),I=1,C)
192 FORMAT((4X,I3,7X,8(E10.4,3X)),/)
199 WRITE(44,1319)
209 FORMAT(//,4X,' LIQ. COMP. FLOW RATES ARE')
219 WRITE(44,2412)
229 WRITE(44,2413)
239 WRITE(44,4315)
249 WRITE(44,2414)
259 WRITE(44,2441)
269 WRITE(44,392)(I,(SL(J,I),J=1,N),I=4,C)
279 WRITE(44,4449)
289 FORMAT(//,4X,' VAPOR AND LIQUID RATE AND TEMPERATURE ARE ://)
299 WRITE(44,4467)
309 FORMAT(4X,42(' - '))
319 WRITE(44,4468)
329 FORMAT(4X,' STAGE, NUMBER',4X,' VAPOR RATE',4X,' LIQUID
339 1 RATE',4X,' TEMPERATURE')
349 WRITE(44,7979)
359 FORMAT(4X,12(' - '),4X,19(' - '),4X,17(' - '),4X,19(' - '),/)
369 WRITE(44,13)(J,V(J),AL(J),T(J),J=1,N)
379 FORMAT(8X,I3,5X,E19.8,4X,E17.8,4X,E19.8)
389 IFAIL=1
399 STOP
409 END
419 CORRECTED VERSION OF PRODUCT FORM OF INVERSE
429 A MATRIX IS TO BE INVERTED
439 INVERTED MATRIX IS IT
449 =====
459 SUBROUTINE GBI(A)
469 INTEGER C,CT
479 COMMON C,CT,N
489 DIMENSION A(CT,CT),TT(29,29),UI(29,29),T(29,29),ETA(29,29)
499 DO 1 I=1,CT
509 UI(I,I)=1.
519 CONTINUE
529 DO 5 K=1,CT
539 ETA(K,K)=1./A(K,K)
549 DO 4 I=1,CT
559 IF(I.EQ.K) GOTO 4
569 ETA(I,K)=-A(I,K)/A(K,K)
579 CONTINUE
589 DO 6 I=1,CT
599 ETA(I,K)=ETA(I,K)-UI(I,K)
609 CONTINUE
619 DO 7 I=1,CT
629 DO 7 J=1,CT
639 T(I,J)=UI(I,J)+ETA(I,K)*UI(K,J)
649 CONTINUE
659 DO 8 I=1,CT
669 DO 8 J=1,CT
679 ETA(I,J)=0.
689 IF(K.NE.1) GOTO 8
699 TT(I,J)=T(I,J)
709 CONTINUE
719 DO 9 I=1,CT
729 DO 9 J=K,CT
739 DO 9 IJ=I,CT

```

```

ETA(I,J)=T(I,IJ)*A(IJ,J)+ETA(I,J)
CONTINUE
DO 10 I=1,CT
DO 10 J=1,CT
A(I,J)=ETA(I,J)
ETA(I,J)=0.
CONTINUE
IF(K.EQ.1) GOTO 5
DO 11 I=1,CT
DO 11 J=1,CT
DO 11 IJ=1,CT
ETA(I,J)=T(I,IJ)*TT(IJ,J)+ETA(I,J)
CONTINUE
DO 12 I=1,CT
DO 12 J=1,CT
TT(I,J)=ETA(I,J)
ETA(I,J)=0.
CONTINUE
CONTINUE
DO 21 I=1,CT
DO 21 J=1,CT
A(I,J)=TT(I,J)
CONTINUE
RETURN
END
SUBROUTINE MTMUL2(A,B)
INTEGER C,CT
COMMON C,CT,N
DIMENSION A(CT,CT),B(CT,CT),D(29,29)
DO 1 I=1,CT
DO 1 J=1,CT
DO 1 IJ=1,CT
D(I,J)=D(I,J)+A(I,IJ)*B(IJ,J)
CONTINUE
DO 2 I=1,CT
DO 2 J=1,CT
B(I,J)=D(I,J)
D(I,J)=0.
CONTINUE
RETURN
END
SUBROUTINE MTMUL1(A,B)
INTEGER C,CT
COMMON C,CT,N
DIMENSION A(CT,CT),B(CT),D(29)
DO 1 I=1,CT
DO 1 II=1,CT
D(I)=A(I,II)*B(II)+D(I)
CONTINUE
DO 2 I=1,CT
B(I)=D(I)
D(I)=0.
CONTINUE
RETURN
END
SUBROUTINE SUBMAT(B,C1)
INTEGER C,CT
COMMON C,CT,N
DIMENSION B(CT,CT),C1(CT,CT)
DO 1 I=1,CT
DO 1 J=1,CT

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```

B(I,J)=B(I,J)-C1(I,J)
CONTINUE
RETURN
END
SUBROUTINE ENL(T,EL)
INTEGER C,CT
COMMON C,CT,N
COMMON /A2/SC
DIMENSION EL(C),SC(14,4)
DO 1 I=1,C
EL(I)=SC(I,1)+SC(I,2)*T+SC(I,3)*T^2+SC(I,4)*T^3
CONTINUE
RETURN
END
SUBROUTINE DENL(T,EL)
INTEGER C,CT
COMMON C,CT,N
COMMON /A2/SC
DIMENSION EL(C),SC(14,4)
DO 1 I=1,C
EL(I)=SC(I,2)+2.*SC(I,3)*T+3.*SC(I,4)*T^2
CONTINUE
RETURN
END
SUBROUTINE ENV(T,EV)
INTEGER C,CT
COMMON C,CT,N
COMMON /A3/SE
DIMENSION EV(C),SE(14,4)
DO 1 I=1,C
EV(I)=SE(I,1)+SE(I,2)*T+SE(I,3)*T^2+SE(I,4)*T^3
CONTINUE
RETURN
END
SUBROUTINE DENV(T,EV)
INTEGER C,CT
COMMON C,CT,N
COMMON /A3/SE
DIMENSION EV(C),SE(14,4)
DO 1 I=1,C
EV(I)=SE(I,2)+SE(I,3)*2.*T+3.*SE(I,4)*T^2
CONTINUE
RETURN
END
SUBROUTINE DIST(T,AK)
INTEGER C,CT
COMMON C,CT,N
COMMON /A1/SA
DIMENSION AK(C),SA(14,4)
DO 1 I=1,C
AK(I)=T*(SA(I,1)+SA(I,2)*T+SA(I,3)*T^2+SA(I,4)*T^3)^3
CONTINUE
RETURN
END
SUBROUTINE DDIST(T,AK)
INTEGER C,CT
COMMON C,CT,N
COMMON /A1/SA
DIMENSION AK(C),SA(14,4)
DO 1 I=1,C
AK(I)=(SA(I,1)+SA(I,2)*T+SA(I,3)*T^2+SA(I,4)*T^3)^3+3.*T*(

```

```
1SA(I,2)+2.*SA(I,3)*T+3.*SA(I,4)*T^2)*(SA(I,1)+SA(I,2)*T  
2+SA(I,3)*T^2+SA(I,4)*T^3)^2  
CONTINUE  
RETURN  
END
```

